

UNIVERSITY OF CROSS RIVER STATE

FACULTY OF ENGINEERING

DEPARTMENT OF MECHANICAL ENGINEERING

COURSE TITLE: ENGINEERING MATHEMANICS III

CHAPTER – 1

MATRICES

Minor – Minor is the determinate value which is obtained by deleting row & coloumn of the particular element and denoted by the symbol , i-rows j-coloum.

$$\text{Ex : } \begin{array}{ccc} 2 & 1 & 3 \\ 4 & 2 & 8 \\ 5 & 6 & 1 \end{array}$$

$$M_{21} = \begin{vmatrix} 1 & 3 \\ 6 & 1 \end{vmatrix} = 1 \cdot 1 - 3 \cdot 6 = 1 - 18 = -17$$

$$M_{32} = \begin{vmatrix} 2 & 3 \\ 4 & 8 \end{vmatrix} = 2 \cdot 8 - 3 \cdot 4 = 16 - 12 = 4$$

Upper triangular Matrix – A matrix is said to be upper triangular if the elements below the main diagoned are zeros.

$$\text{Ex. } \begin{array}{ccc} 1 & 5 & 9 \\ 0 & 3 & 7 \\ 0 & 0 & 8 \end{array}$$

Elementary transformations : – The following operations three of which refer to rows are known as elementary transformations.

- I. The interchange of any two rows (R_i)
- II. The multiplication of any row by a non- zero scalar (kR_i)
- III. The addition of a constant multiple of the elements of any row to the corresponding elements of any other row ($R_i + kR_j$)

Equivalent matrix – Two matrices A and B are said to be equivalent if one can be obtained from the other by a sequence of elementary transformations.

Rank of a matrix : A matrix is said to be of rank 'r' if

- (i) It has atleast one non-zero minor of order 'r'
- (ii) Every minor of order higher than 'r' vanishes.

The rank of a matrix A shall be denoted by the symbol $e(A)$.

Engineering Mathematics – III

3

Working Rule :

Step – I : Conver the matrix to the upper triangular form.

Step – II : The no.of non-zero rows is the rank of the matrix

Example – 1 :

Find the rank of the matrix

$$\begin{bmatrix} 3 & 1 & 2 \\ 6 & 2 & 4 \\ 3 & 1 & 2 \end{bmatrix}$$

Solution :

$$A = \begin{bmatrix} 3 & 1 & 2 \\ 6 & 2 & 4 \\ 3 & 1 & 2 \end{bmatrix}$$

$$\sim \begin{bmatrix} 3 & 1 & 2 \\ 0 & 0 & 8 \\ 3 & 1 & 2 \end{bmatrix} \rightarrow R_2 + 2R_1$$

$$\sim \begin{bmatrix} 3 & 1 & 2 \\ 0 & 0 & 8 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\sim \begin{bmatrix} 3 & 1 & 2 \\ 0 & 0 & 8 \\ 0 & 0 & 0 \end{bmatrix}$$

$R_3 - R_1$

$2R_3 - R_2$

$$p(A) = 2$$

Consistency : A system of equations are said to be consistent if either they will have unique solution or many solutions and said to be inconsistent if they will have no solution.

$$2x + 3y = 8$$

$$x + 2y = 5$$

$$x - y = 10$$

$$x - 2y = 4$$

$$2x + 4y = 10$$

$$3x - 3y = 15$$

(unique solution)

(many solutions)

(No solution)

Consistency of a system of linear equations : -

Consider a system of m linear equations

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\dots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

.....(1)

4

Engineering Mathematics – III

Containing the n unknowns x_1, x_2, \dots, x_n .

Writing the above equations in matrix form we get.

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}, \quad B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

$$C = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \dots & \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{bmatrix}$$

A is the co-efficient matrix and

C is called augmented matrix

Rouche's Theorem : (Without proof)

The system of equations (1) is consistent if and only if the co-efficient matrix A and the augmented matrix C are of some rank otherwise the system is inconsistent.

Procedure to test the consistency of a system of equations in x unknowns.

Find the ranks of the co-efficient matrix A and the augmented matrix ' C ' by reducing to the upper triangular form by elementary row operations.

(a) Consistent equations : If Rank $A =$ Rank C

(i) Unique solution Rank $A =$ Rank $C = n$

Where $n =$ number of unknowns.

(ii) Infinite solution : Rank $A =$ Rank $C = r, r < n$.

(b) Inconsistent equations if Rank $A \neq$ Rank C

Example – 2 :

Show that the equations

$2x + 6y = -11, 6x + 20y - 6z = -3, 6y - 18z = -1$ are not consistent.

Solution :

Writing the above equations in matrix form

$$\begin{array}{ccc|c} 2 & 6 & 0 & -11 \\ 6 & 20 & -6 & -3 \\ 0 & 6 & -18 & -1 \end{array}, \quad AX=B$$

$$\begin{array}{ccc|c} \hline A & X & B \\ \hline \end{array}$$

6

Engineering Mathematics – III

$$\begin{array}{ccc|c}
 1 & 5 & 5 & 5 \\
 & 3 & 7 & 4 \\
 & 121 & 41 & \\
 \hline
 0 & 5 & -5 & -5 \\
 \hline
 0 & 0 & 0 & 0
 \end{array}
 \quad R + \frac{1}{3} R_3$$

Here Rank of A = Rank of C.

Hence the equations are consistent.

But the rank is less than 3 i.e. the number of unknowns.

So its solutions are infinite

$$\begin{array}{ccc|c}
 & 3 & 7 & 4 \\
 1 & 5 & 5 & 5 \\
 & 121 & 11 & 33 \\
 \hline
 & & & 0
 \end{array}
 \quad x$$

$$\begin{array}{ccc}
 x & y & z \\
 \frac{121}{5} & \frac{11}{5} & \frac{33}{5}
 \end{array}
 \quad \text{or } 11y - z = 3$$

Let $z = k$, $11y - k = 3$ or $y = \frac{11k + 3}{11}$

$$x = \frac{16k + 7}{11}$$

Example – 4 :

Determine the values of Z & μ so that the following equations have (i) no solution (ii) a unique solution (iii) infinite number of solutions.

$$x + y + z = 6, \quad x + 2y + 3z = 10, \quad x + 2y + Zz = \mu$$

Solution :

Writing the above equations in matrix form we have

$$\begin{array}{ccc|c}
 1 & 1 & 1 & 6 \\
 1 & 2 & 3 & 10 \\
 1 & 2 & Z & \mu
 \end{array}
 \quad XZ B$$

A

Engineering Mathematics – III

7

$$\begin{array}{l} \backslash \quad AX=B \\ \quad C=[A:B] \\ \\ C=123:10\sim 01 \end{array} \quad \begin{array}{ccccccc} 1 & 1 & 1 & : & 6 \\ & & & & 2 & : & 4 \\ \\ 1 & 3 & & & 0 & 1 & \\ \\ 1 & 1 & 1 & : & 6 \\ \sim & 1 & 2 & : & 4 \\ \\ 00310 & & & & R_3 & R_2 \end{array}$$

- (i) There is no solution = b p (A) G p(C)
i.e. $Z - 3 = 0$ or $Z = 3$ & $\mu - 10 = 0$ or $\mu = 10$
- (ii) There is a unique solution if $p(A) = p(C) = 3$
i.e., $Z - 3 = 0$ or $Z = 3$ and μ have any value
- (iii) There are infinite solution of $p(A) = p(C) = 2$
 $Z - 3 = 10$ or $Z = 13$ and $\mu - 10 = 0$ or $\mu = 10$

Assignments

1. Find the rank of the matrix $\begin{array}{ccc} 1 & 2 & 3 \\ & & 4 \end{array}$
2. Test the consistency & solve $\begin{array}{c} 310 \\ 4x - 5y + z = 2 \end{array}$

$$3x + y - 2z = 9$$

$$x + 4y + z = 5$$

3. Determine the values of a & b for which the system of equations $3x - 2y + z = b$
 $5x - 8y + 9z = 3$
 $2x + y + az = -1$

(i) has a unique solution (ii) has no solution (iii) has infinite solution.

□ □ □⁶

CHAPTER – 2

LINEAR DIFFERENTIAL EQUATIONS

Introduction :

The Mathematical formulation of many problems in science, Engineering and Economics gives rise to differential Equations.

For example : The problem of motion of a satellite

- The flow of fluids.
- The flow of current in an electric circuit
- The growth of population
- The Conduction of heat in rod etc leads to differential equations

Definition of Differential Equation :

A differential equation is an equation involving derivatives of one or more dependent variables with respect to one or more independent variables.

There are two types of Differential Equation

1. Ordinary differential Equation
2. Partial differential Equation

Example : $\frac{dy}{dx} = x^2$

(a) $\frac{dy}{dx} = y + x$

(b) $\frac{d^3y}{dx^3} + 3 \frac{d^2y}{dx^2} + 2 \frac{dy}{dx} + y = 0$

(c) $\frac{u}{t} = \frac{u^2}{t^4}$

Linear differential Equation :

Linear differential Equations are those in which the dependent variable and its derivatives occur only in the first degree and are not multiplied together.

The differential Equation of the form

$$\frac{d^n y}{dx^n} + k_1 \frac{d^{n-1} y}{dx^{n-1}} + k_2 \frac{d^{n-2} y}{dx^{n-2}} + \dots + k_n y = X \dots \dots \dots (1)$$

Engineering Mathematics – III

9

Is known as linear differential Equation with constant coefficients. Where k_1, k_2, \dots, k_n are constant, X is the function of x .

There are two types of linear differential Equation

1. Homogeneous LDE
2. Non Homogeneous LDE

Homogeneous Linear Differential Equation :

If RHS of Equation (1) is Equal to zero then we get homogeneous LDE.

$$\text{ie } \frac{d^2 y}{dx^2} + k_1 \frac{d y}{dx} + k_2 y = 0$$

Where $f(x)$ is the function of ' x '

The general solution format of Equation (1) of the form (C.S = C.F + P.I)

Where C.S. – Complete Solution

C.F – Complementary function

P.I – Particular integral

So complete solution of Equation becomes ($y = C.F + P.I$)

Note - 1: In case of Homogeneous LDE

$$C.S = C.F \text{ [where P.I} = 0]$$

Note - 2 : In case of Non-Homogeneous LDE

$$C.S = C.F + P.I$$

Operator :

Denoting $\frac{d}{dx}, \frac{d^2}{dx^2}, \frac{d^3}{dx^3}, \dots$ by D, D^2, D^3 etc.

$$\frac{d}{dx}, \frac{d^2}{dx^2}, \frac{d^3}{dx^3}$$

So that $\frac{d}{dx} = D$

$$\frac{d^2}{dx^2} = D^2$$

.....

$$\frac{d^n}{dx^n} = D^n$$

Where D – Derivative

Then $\frac{1}{D}$ – Integration

Then operator form of equation (1) becomes

$$D^n y + k_1 D^{n-1} y + k_2 D^{n-2} y + \dots + k_n y = X$$

$$\rightarrow (D^n + k_1 D^{n-1} + k_2 D^{n-2} + \dots + k_n) y = X$$

$$\rightarrow F(D) y = X \text{ (2)}$$

Where $F(D) = D^n + k_1 D^{n-1} + k_2 D^{n-2} + \dots + k_n$ of function D

Auxiliary Equation (AE)

Putting the coefficient of y equal to Zero in Equation (2) we get an Auxiliary Equation. i.e.

$$F(D)=0$$

$$\text{i.e. } D^n + k_1 D^{n-1} + k_2 D^{n-2} + \dots + k_n = 0$$

Depending value of 'D' in Auxiliary Equation, complementary function are different types.

Case - I : If roots are real & Different

Let m_1 & m_2 are two real roots and different

$$\text{i.e. } m_1 \neq m_2$$

$$\text{Then C.F} = C_1 e^{m_1 x} + C_2 e^{m_2 x}$$

Where C_1, C_2 , are arbitrary constant

Case - II : If roots are real & Equal

Let m_1 & m_2 are two real roots & Equal

$$\text{i.e. } m_1 = m_2$$

$$\text{The C.F} = (C_1 + C_2 x) e^{m_1 x}$$

Similarly if $m_1 = m_2 = m_3$ (Three roots are Equal)

$$\text{Then C.F} = (C_1 + C_2 x + C_3 x^2) e^{m_1 x}$$

Case - III : If roots are Complex conjugate

Let $m_1 = \alpha \pm i\beta$ are conjugate complex root

$$\text{Then C.F} = e^{\alpha x} \{C_1 \cos \beta x + C_2 \sin \beta x\}$$

Case - IV : If two conjugate complex roots are equal

Let $m_1 = m_2 = \alpha \pm i\beta$ are equal

$$\text{Then C.F} = e^{\alpha x} \{C_1 + C_2 x\} \cos \beta x + (C_3 + C_4 x) \sin \beta x$$

Example – 1 : $d^2 y / dx^2 + 8 dx / dx + 15y = 0$ (1)

$$\text{Solve } d^2 y / dx^2 + 8 dx / dx + 15y = 0 \dots\dots(1)$$

Solution : The operator from of equation (1) becomes

$$(D^2 - 8D + 15) y = 0$$

So Auxiliary Equation

$$D^2 - 8D + 15 = 0$$

$$\rightarrow (D-3)(D-5) = 0$$

$$\rightarrow D = 3, 5$$

$$\text{Then C.F} = C_1 e^{3x} + C_2 e^{5x}$$

So complete Solution

$$y = C_1 e^{3x} + C_2 e^{5x} \quad (\text{Ans})$$

Engineering Mathematics – III

11

Example – 2 :

$$\text{Solve } \frac{d^2 y}{dx^2} - 6 \frac{dy}{dx} + 9y = 0$$

Solution : The operator from of given equation is

$$(D^2 - 6D + 9) y = 0$$

$$\text{Then A.E } D^2 - 6D + 9 = 0$$

$$\rightarrow (D-3)^2 = 0$$

$$\rightarrow D = 3, 3$$

$$\text{C.F} = (C_1 + C_2 x) e^{3x}$$

$$\text{Then C.S}_1 y = (C_1 + C_2 x) e^{3x} \quad (\text{Ans})$$

Example – 3 :

$$\text{Solve } (D^2 + 4D + 5) y = 0$$

Solution : So A.E $D^2 + 4D + 5 = 0$

$$D = \frac{-4 \pm \sqrt{16 - 4 \cdot 1 \cdot 5}}{2 \cdot 1}$$

$$= \frac{-4 \pm \sqrt{4}}{2}$$

$$= \frac{-4 \pm 2i}{2} = -2 \pm i$$

$$\text{Then C.F} = e^{-2x} \{C_1 \cos x + C_2 \sin x\} \quad (\text{Ans})$$

Procedure to finding particular integral.

We know that $F(D) y = X$

$$\rightarrow y = \frac{X}{F(D)}$$

Depending upon nature of 'X', Particular integral are different types

Case -1 : When $X = e^{ax}$

$$\text{Then P.I} = \frac{e^{ax}}{F(a)} \text{ where } D = a$$

$$\text{If } F(a) \neq 0, \text{ Then PI} = \frac{X e^{ax}}{F(a)} \text{ provided } F'(a) \neq 0$$

$$\text{If } F'(a) = 0, \text{ Then } \frac{X^2 e^{ax}}{F(a)} \text{ provided } F''(a) \neq 0$$

PI And so on.

12

Engineering Mathematics – III

Case – 2 : When $X = \sin(ax + b)$ or $\cos(ax + b)$

$$\text{Then P.I.} = \frac{\sin(ax + b)}{F(D)^2} \text{ Put } D = -a$$

But not $D = -a$

$$\frac{\sin(ax + b)}{F(a^2)} \text{ provided } F(-a^2) \neq 0$$

If $F(-a^2) = 0$, The above rule Fails & We proceed further

$$\text{ie P.I.} = \frac{x \sin(ax + b)}{F(a^2)}, \text{ Provided } F'(-a^2) \neq 0$$

$$= \frac{x \sin(ax + b)}{F(a^2)}$$

If $F'(-a^2) = 0$, Then P.I. $x^2 \frac{\sin(ax + b)}{F(a^2)}$, Provided $F''(-a^2) \neq 0$

And so on

Case – 3 : When $X = e^{axv}$, Where $v =$ function of ' x '

$$\text{Then P.I.} = \frac{e^{axv}}{F(D)}$$

$$= \frac{e^{axv}}{F(D - a)}$$

Similarly when $X = e^{-axv}$

$$\text{Then P.I.} = \frac{e^{-axv}}{F(D + a)}$$

Case – 4 : When $X = x_m$ (ie, x, x^2, x^3, \dots)

$$\text{Then P.I.} = \frac{x_m}{F(D)} = [F(D)]^{-1} x_m$$

Convert $F(D)$ into $\{1 + \Phi(D)\}$ or $\{1 - \Phi(D)\}$ by taking D_m (if possible). Then by using Binomial Theorem we find solution.Case – 5 : When $X = xv^x$

$$\text{Then P.I.} = \frac{xv^x}{F(D)}$$

$$= \frac{xv^x}{F(D)} = \frac{F'(D)}{F(D)} \text{ Where } F'(D) \text{ is the Derivative of } F(D)$$

Engineering Mathematics – III

Case – 6 : When x = is any other function

Then P.I $\frac{x}{F D}$

Convert F (D) into (D – α) or (D + α) factor form

Then if $x = e^{ax}$ $X e^{atdx}$ $x = e^{-ax}$ $X e^{atdx} D$

Example – 4 : D if

Find P. I of $(D^2 + 6D + 3) y = e^{2x}$

Solution : P. I. $\frac{e^{2x}}{D^2 + 6D + 3}$ put $D = a$

i.e. $D = 2$

Then P.I. $\frac{e^{2x}}{(2)^2 + 6(2) + 3}$

$\frac{e^{2x}}{19}$ (Ans)

Example – 5 :

$\frac{d^3 y}{dx^3} - 3 \frac{d^2 y}{dx^2} + 4 \frac{dy}{dx} - 2 y = e^x + \cos x$

Solution : The operator form of given equation becomes

$(D^3 - 3D^2 + 4D - 2) y = e^x + \cos x$

So A.E $D^3 - 3D^2 + 4D - 2 = 0$

$\rightarrow D - 1, 1 \pm i$

$\rightarrow D = 1, 1 \pm i$

C.F = $C_1 e^x + e^x \{C_2 \cos x + C_3 \sin x\}$

Then PI $\frac{e^x}{D^3 - 3D^2 + 4D - 2}$

$\frac{e^x}{D^3 - 3D^2 + 4D - 2}$	$\frac{\cos x}{D^3 - 3D^2 + 4D - 2}$
$\frac{e^x}{(D-1)(D-2)(D-1-i)(D-1+i)}$	$\frac{\cos x}{(D-1)(D-2)(D-1-i)(D-1+i)}$
$\frac{e^x}{(D-1)(D-2)(D-1-i)(D-1+i)}$	$\frac{\cos x}{(D-1)(D-2)(D-1-i)(D-1+i)}$

14

Engineering Mathematics – III

$$e^x \frac{\cot x}{3D-1}$$

$$x \frac{1}{3D-1}$$

$$x e^x \frac{3D \cos x \cos x}{9D^2 - 1}$$

$$x e^x \frac{3 \sin x \cos x}{9 - 1} = x e^x \frac{3 \sin x \cos x}{8}$$

So C.S $y = C e^x + e^x \{C \cos x + C_3 \sin x\} + x e^x \frac{1}{8} (3 \sin x + \cos x)$

Solution : Find the P.I. of $(D^3 + 1)y = e^x \cos x + \sin 3x$

$$e^x \cos x \sin$$

$$e^x \frac{\cos x}{D-1} \frac{\sin 3x}{D^2 D - 1}$$

$$e^x \frac{\cos x}{D^3 - 3D^2 + 2D} \frac{\sin 3x}{9D - 4}$$

$$e^x \frac{\cos x}{D^3 - 3D^2 + 2D} \frac{\sin 3x}{9D - 4}$$

$$e^x \frac{\cot x}{D^3(1)} \frac{\sin 3x}{3D - 219D}$$

$$e^x \frac{\cos x}{2D^2 D - 1} \frac{\sin 3x}{19D^2 - 9D}$$

$$e^x \frac{2D \cos x}{4D^2 - 11} \frac{\sin 3x}{81D^2} = \frac{2D \cos x \sin 3x}{4D^2 - 11} \frac{1}{81D^2}$$

$$e^x \frac{2 \sin x \cos x}{4 - 1} \frac{\sin 3x}{1819} \frac{27 \cos 3x}{1}$$

$$e^x \frac{2 \sin x \cos x}{5}$$

$$\frac{730 \sin 3x + 27 \cos 3x}{5}$$

(Ans)

Engineering Mathematics – III

15

Example – 7 :

$$d^2 y$$

$$\text{Solve } \frac{d^2 y}{dx^2} + 9y = x \cos x$$

Solution : dx

$$\text{The operator form is } (D^2 + 9)y = x \cos x$$

$$\text{So A.E } D^2 + 9 = 0$$

$$\rightarrow D^2 = -9$$

$$\rightarrow D = \pm \sqrt{-9}$$

$$\rightarrow D = \pm 3i$$

$$\text{C.F} = C_1 \cos 3x + C_2 \sin 3x$$

Now P.I $x \cos x$

$$D^2 + 9$$

$$\text{Here } F(D) = D^2 + 9$$

$$F'(D) = 2D$$

$$\text{Then PI} = x \frac{F(D)}{F'(D)} V$$

$$x \frac{D^2 + 9}{9} \frac{F(D)}{2D} \cos x \quad \text{put } D^2 = -1$$

$$x \frac{2D + 9}{D^2 + 9} \frac{\cos x}{2} =$$

$$\frac{x \cos x}{8} + \frac{2D \cos x}{8D^2 + 9}$$

$$\frac{x \cos x}{8} + \frac{2 \sin x}{8 \cdot 8}$$

$$\frac{x \cos x}{8} + \frac{\sin x}{32} + \frac{4x \cos x \sin x}{32}$$

$$\text{So C.S } y = C \cos x + C \frac{4x \cos x \sin x}{32} \quad (\text{Ans})$$

Example – 8 : $\frac{d^2 y}{dx^2} + 4y = x^2 \sin 3x$

$$\text{Solve } \frac{d^2 y}{dx^2} + 4y = x^2 \sin 3x$$

Solution : dx

The operation form given equation becomes

$$(D^2 + 4)y = x^2 \sin 3x$$

16

Engineering Mathematics – III

So A.E. $D^2 + 4 = 0$

→ $D = -2$

→ $D = 2$

→ $D = \pm 2i$

C.F = $C_1 \cos 2x + C_2 \sin 2x$

Then P.I $\frac{1}{4} \frac{1}{D^2 + 4} x^2$

$\frac{1}{4} \frac{D^2 + 4}{4} x^2$

$\frac{1}{4} \frac{1}{4} x^2 = \frac{1}{16} x^2$ by using Binomial theorem

$\frac{1}{4} \frac{1}{4} x^2 = \frac{1}{16} x^2$

$\frac{1}{4} \frac{1}{4} x^2 = \frac{1}{16} x^2$

$\frac{1}{4} \frac{1}{4} x^2 = \frac{1}{16} x^2$

$\frac{1}{4} \frac{1}{4} x^2 = \frac{1}{16} x^2$

So C.S $y = C_1 \cos 2x + C_2 \sin 2x + \frac{2x^2}{8}$ (Ans)

Other Method for finding P. I :

Method of variation of Parameters :

This method is applies to equations of the form

$$y'' + py' + qy = x$$

Where p, q & x are function of x.

Then P. I = $\int y_1 \frac{y_2 x}{W} dx - \int y_2 \frac{y_1 x}{W} dx$

Where y_1 & y_2 are the solution of $y'' + py' + qy = 0$ of the form $= c_1 y_1 + c_2 y_2$ & w is called wronskian of y_1 & y_2

Calculate by formula $w(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$

Engineering Mathematics – III

Example – 9 :

Solve $D^2 y - y = \operatorname{cosec} x$ Solution : $D^2 y - y = \operatorname{cosec} x$

The operator form of given equation is

$$(D^2 - 1)y = \operatorname{cosec} x$$

So A.E $D^2 - 1 = 0$

$$\rightarrow D^2 = 1$$

$$\rightarrow D = \pm 1 \quad \therefore y_1 = \cos x, y_2 = \sin x$$

$$\text{C.F.} = C_1 \cos x + C_2 \sin x$$

Here $y_1 = \cos x, y_2 = \sin x$

$$W(y_1, y_2) = \begin{vmatrix} \cos x & \sin x \\ -\sin x & \cos x \end{vmatrix}$$

$$= \cos^2 x + \sin^2 x = 1$$

$$\text{Then P.I.} = \cos x \int \frac{\sin x \operatorname{cosec} x}{1} dx + \sin x \int \frac{\sin x \operatorname{cosec} x}{1} dx$$

$$= \cos x \int \frac{1}{\sin x} dx + \sin x \int \frac{1}{\cos x} dx$$

$$= \cos x \int \operatorname{cosec} x dx + \sin x \int \sec x dx$$

$$= -\cos x \ln |\sin x| + \sin x \ln |\cos x| - x \cos x$$

$$\text{So C.S. } y = C_1 \cos x + C_2 \sin x + \sin x \ln |\sin x| - x \cos x$$

(Ans.)

Partial Differential Equation

Let $z = f(x, y)$ be a function containing two independent
Dependent variable.variable x & y and z is theNotation : Let $z = f(x, y)$ be a function of x & y

$$\text{Then } \frac{\partial z}{\partial x} = p \quad \frac{\partial z}{\partial y} = q$$

$$\frac{\partial^2 z}{\partial x^2} = r \quad \frac{\partial^2 z}{\partial y^2} = t$$

$$\frac{\partial^2 z}{\partial x \partial y} = s$$

$$\frac{\partial^2 z}{\partial x^2} = r$$

Formation of Partial differential Equation

A partial differential equation can be formed by

(i) Eliminating arbitrary constant.

(ii) Eliminating arbitrary function.

18

Engineering Mathematics – III

Example – 10 :

Form a partial differential equation by eliminating function

$$\text{Solution : } Z = f(x^2 + y^2) \quad \dots(1)$$

Differentiating partially w.r.t. x & y in equation (1) we get

$$\frac{\partial Z}{\partial x} = 2x f'(x^2 + y^2) \quad \text{(taking y as a constant)}$$

$$\rightarrow p = f'(x^2 + y^2) \cdot 2x \quad \dots(2)$$

$$\text{Similarly } q = f'(x^2 + y^2) \cdot 2y \quad \dots(3)$$

$$\text{Dividing (2) \& (3) we get } \frac{p}{q} = \frac{2x}{2y} = \frac{x}{y}$$

$$\frac{p}{q} = \frac{x}{y}$$

$$\rightarrow py - qx = 0 \quad (\text{Ans.})$$

Linear Equation of the First order :

A Linear partial differential equation of the 1st order is of the form

$$Pp + Qq = R$$

Where P, Q & R are function of x, y, z.

This equation also known as Lagrange's Linear equation

NOTE :

The general solution of the linear partial differential equation $Pp + Qq = R$ is

$$\phi(a, b) = 0$$

$$\text{Or } a = \phi(b)$$

$$\text{Or } b = \phi(a)$$

Where ϕ is an arbitrary function & $u(x, y, z) = a$ & $v(x, y, z) = b$ form the solution of the equation

$$\frac{dx}{P} = \frac{dy}{Q} = \frac{dz}{R}$$

Then that can be solved by two methods

(1) Method for Grouping

(2) Method for Multipliers

Method or grouping :

Take any two fraction from Subsidiary Equation such that the 3rd variable is absent or it may be cancelled.

For example take $\frac{dx}{P} = \frac{dy}{Q}$ (such that z may be absent)

Engineering Mathematics – III**19**

After Integration we get $f(x, y) = a$

Similarly we take $\frac{dy}{Q} \quad \frac{dz}{R}$

After Integration $f(y, z) = b$

So general solution is $a = \phi(b)$

or $b = \phi(a)$

or $\phi(a, b) = 0$

Method for Multipliers

Let us choose the multiplier's (P', Q', R') such

That $PP' + QQ' + RR' = 0$

Then we write $P'dx + Q'dy + R'dz = 0$

On Integration we get $f(x, y, z) = a$

Similarly choosing the multipliers (P'', Q'', R'') such that

$PP'' + QQ'' + RR'' = 0$

On Integration we get $g(x, y, z) = b$

So general solution is $a = \phi(b)$ or $\phi(a, b) = 0$

Example – 11 :

Solve $y^2z dx + z^2x dy = y^2x dz$

Solution :

It is of the form $Pp + Qq = R$

Where $P = y^2z, Q = z^2x, R = y^2x$

So its S.E $\frac{dx}{y^2z} \frac{dy}{z^2x} \frac{dz}{y^2x}$

Taking 1st and 3rd fraction, we get

$$\frac{-dx}{yz} \frac{dy}{y^2x} \quad (\text{Here 3rd variable } y^2 \text{ is cancelled})$$

$$\rightarrow xdx = zdx$$

Integrating both sides we get $xdx = zdx$

$$\rightarrow \frac{x^2}{2} = \frac{z^2}{2} + C$$

$\rightarrow x^2 - z^2 = 2C = \text{const}$
Similarly taking 2nd and 3rd

$$\text{i.e. } \frac{dy}{z^2x} \frac{dz}{y^2x}$$

$$\rightarrow y^2dy = z^2dz$$

20

Engineering Mathematics – III

Integrating both sides we get

$$\rightarrow \frac{y^3}{3} - \frac{z^3}{3} = C$$

$$\rightarrow y^3 - z^3 = 3C = b$$

So general solution in $x^2 - z^2 = \phi(y^3 - z^3)$

(Ans.)

Example – 12 :

$$\text{Solve } x(z^2 - y^2) p + y(x^2 + y^2) q = z(y^2 - x^2)$$

Solution :

It is the equation of the form

$$Pp + Qq = R$$

$$\text{Where } P = x(z^2 - y^2) \quad Q = y(x^2 + y^2) \quad R = z(y^2 - x^2)$$

$$\text{So its S.E is } \frac{dx}{x(z^2 - y^2)} + \frac{dy}{y(x^2 + y^2)} + \frac{dz}{z(y^2 - x^2)}$$

Let us choose multipliers (x, y, z) i.e. $P' = x, Q' = y, R' = z$

$$\text{Such that } x \cdot x(z^2 - y^2) + y \cdot y(x^2 + y^2) + z \cdot z(y^2 - x^2)$$

$$= x^2z^2 - x^2y^2 + y^2x^2 + y^2y^2 + z^2y^2 - z^2x^2$$

$$= 0$$

Then we write $x dx + y dy + z dz = 0$

On integration we set

$$\frac{x^2}{2} + \frac{y^2}{2} + \frac{z^2}{2} = C$$

$$\rightarrow x^2 + y^2 + z^2 = 2C = a$$

Again choose the multipliers $\frac{1}{x}, \frac{1}{y}, \frac{1}{z}$ i.e. $P'' = \frac{1}{x}, Q'' = \frac{1}{y}, R'' = \frac{1}{z}$

$$\text{Such that } \frac{1}{x} \cdot x(z^2 - y^2) + \frac{1}{y} \cdot y(x^2 + y^2) + \frac{1}{z} \cdot z(y^2 - x^2)$$

$$= z^2 - y^2 + x^2 - z^2 + y^2 - x^2 = 0$$

$$\text{Then } \frac{1}{x} dx + \frac{1}{y} dy + \frac{1}{z} dz = 0$$

On integration we get

$$\log x + \log y + \log z = \log b$$

$$\rightarrow \log(xyz) = \log b$$

$$\rightarrow xyz = b$$

So general solution in $x^2 + y^2 + z^2 = \phi(xyz)$ (Ans)

Assignment

Solve the followings :

1. $\frac{d^2 y}{dx^2} + 3 \frac{dy}{dx} + 2y = 4 \cos 2x$
2. $y'' + 3y' + 2y = 4 \cos 2x$
3. $\frac{d^2 y}{dx^2} + 2 \frac{dy}{dx} + y = x e^x$
4. $(D^2 + a^2)y = k \cos (ax + b)$
5. $(D - 2)^2 y = 8 (e^{2x} + \sin 2x)$
6. $\frac{d^3 y}{dx^3} + \frac{d^2 y}{dx^2} + \frac{dy}{dx} + y = x$



CHAPTER – 3

LAPLACE TRANSFORMS

GAMMA FUNCTION :

The gamma function is defined as

$$\Gamma(n) = \int_0^{\infty} e^{-x} x^{n-1} dx, n > 0 \quad \dots(1)$$

It defines a function of n for positive values of n.

Value of $\Gamma(1)$:

We have,

$$\Gamma(1) = \int_0^{\infty} e^{-x} x^{1-1} dx = \int_0^{\infty} e^{-x} dx = \left[-e^{-x} \right]_0^{\infty} = 1 \quad \dots(2)$$

Hence, $\Gamma(1) = 1$

Reduction formula for $\Gamma(n)$:

We have,

$$\Gamma(n+1) = \int_0^{\infty} e^{-x} x^n dx \quad [\text{Integrating by parts}]$$

$$\Gamma(n+1) = \left[-x^n e^{-x} \right]_0^{\infty} + n \int_0^{\infty} e^{-x} x^{n-1} dx = 0 + n\Gamma(n)$$

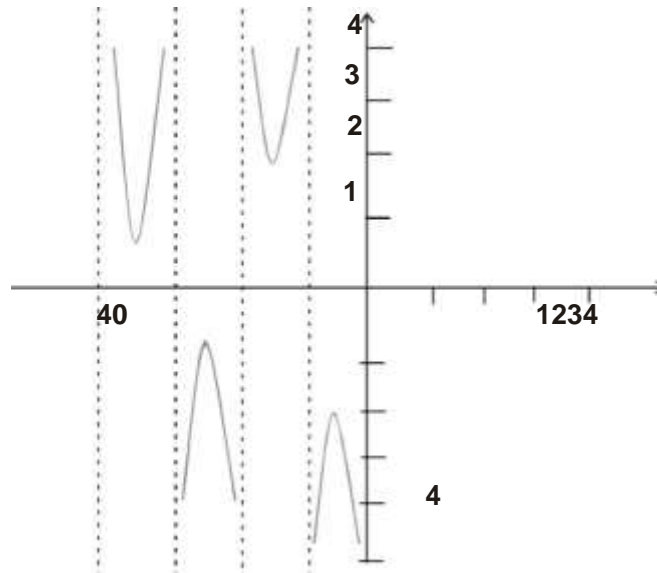
$$\Gamma(n+1) = n\Gamma(n), \dots\dots\dots (3)$$

which is the reduction formula for $\Gamma(n)$.

Using the reduction formula for $\Gamma(n)$, we can write the value of

$$\Gamma(n) \text{ in the form, } \Gamma(n) = \Gamma(1) \dots\dots\dots (4)$$

Thus (1) and (4) together give a complete definition of $\Gamma(n)$ defined for all values of n except when n is zero or a negative integer and its graph is as shown in the following figure.



VALUE OF F(n) IN TERMS OF FACTORIAL

Using $F(n + 1) = nF(n)$ successively, we get

$$F(2) = F(1+1) = 1 \times F(1) = 1!$$

$$F(3) = F(2+1) = 2 \times F(2) = 2 \times 1 = 2!$$

$$F(4) = F(3+1) = 3 \times F(3) = 3 \times 2 = 3!$$

In general $F(n + 1) = n!$, provided n is a positive integer.

Taking $n = 0$, it defines $0! = F(1) = 1$

Thus, $F(n + 1) = n!$ (for $n = 0, 1, 2, 3, \dots$) (5)

Value of $F_{\frac{1}{2}}$:

We have,

$$\frac{1}{2} \int_0^{\infty} e^{-x} x^{1/2} dx \quad [\text{Put } x = y^2 \text{ so that } dx = 2y dy]$$

$$\frac{1}{2} \int_0^{\infty} 2 e^{-y^2} y dy, \text{ Which is also } \int_0^{\infty} e^{-x^2} dx \quad [\text{Put } x = r \cos \theta \text{ and } y = r \sin \theta]$$

$$\int_0^{\infty} e^{-r^2} r dr = \int_0^{\frac{\pi}{2}} \int_0^{\infty} e^{-r^2} r dr d\theta = \int_0^{\frac{\pi}{2}} \left[-\frac{1}{2} e^{-r^2} \right]_0^{\infty} d\theta = \int_0^{\frac{\pi}{2}} \frac{1}{2} d\theta = \frac{1}{2} \left[\theta \right]_0^{\frac{\pi}{2}} = \frac{1}{2} \left(\frac{\pi}{2} - 0 \right) = \frac{\pi}{4}$$

24

Engineering Mathematics – III

Hence $\frac{1}{2} \sqrt{1.772} \dots(6)$

Example – 1 : 2

Evaluate, $\frac{{}^3P_2 \cdot {}^5P_1}{{}^8P_3}$

Solution : $(4) \cdot (6) \cdot (8)$

We have, $\frac{{}^3P_2 \cdot {}^5P_1}{{}^8P_3}$

$$\frac{(3 \cdot 2) \cdot (5 \cdot 1)}{(8 \cdot 7 \cdot 6)}$$

$$\frac{6 \cdot 5}{336}$$

$$\frac{30}{336} = \frac{5}{56} = 0.0892857$$

9676800

Example – 2 :

Evaluate $F(-3.5)$

Solution :

We know that, $(n) \binom{n-1}{n}$

For all n except n is zero or a negative integer.

Now, we have,

$$F = \frac{\binom{3.5}{-3.5}}{\binom{2.5}{3.5} \binom{2.5-1}{2.5}} = \frac{\binom{1.5}{3.5}}{\binom{2.5}{3.5} \binom{1.5}{2.5}}$$

$$\frac{(1.5 \cdot 1)}{(3.5)(2.5)(1.5)} \cdot \frac{(0.5)}{(3.5)(2.5)(1.5)}$$

$$\frac{(0.5)}{(3.5)(2.5)(1.5)(0.5)} = \frac{1}{(3.5)(2.5)(1.5)(0.5)} = 0.27$$

$\therefore F(-3.5) = 0.27$

Engineering Mathematics – III**25****Laplace transforms :****Definition :**

Let $f(t)$ be a function of t defined for all positive values of t . Then the Laplace transform of $f(t)$, denoted by $L\{f(t)\}$ is defined by

$$L\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt$$

Provided that the integral exists. s is a parameter which may be a real or complex number.

$L\{f(t)\}$ being clearly a function of s is briefly written as $f(s)$.

i.e., $L\{f(t)\} = f(s)$.

This implies that, $f(t) = L^{-1}\{f(s)\}$

Then $f(t)$ is called the inverse Laplace transform of $f(s)$.

The symbol L , which transforms $f(t)$ into $f(s)$, is called the Laplace transformation operator.

CONDITIONS FOR THE EXISTENCE :

The Laplace transform of $f(t)$ i.e., $\int_0^{\infty} e^{-st} f(t) dt$ exists for $s > a$, if

- (i) $f(t)$ is continuous
and (ii) $\lim_{t \rightarrow \infty} \{e^{-at} f(t)\}$ is finite.

TRANSFORMS OF ELEMENTARY FUNCTIONS :

The direct application of the definition gives the following formulae :

$$(1) \quad L\{1\} = \frac{1}{s} \quad (s > 0)$$

$$(2) \quad L\{t^n\} = \frac{n!}{s^{n+1}}, \quad \text{when } n = 0, 1, 2, 3, \dots$$

$$\frac{(n-1)!}{s^n}, \quad \text{otherwise } (s > 0)$$

$$(3) \quad L\{e^{at}\} = \frac{1}{s-a} \quad (s > a)$$

$$(4) \quad L\{\sin at\} = \frac{a}{s^2 + a^2} \quad (s > 0)$$

$$(5) \quad L\{\cos at\} = \frac{s}{s^2 + a^2} \quad (s > 0)$$

$$(6) \quad L\{\sin h at\} = \frac{a}{s^2 - a^2} \quad (s > |a|)$$

(7) $L\{\cosh at\} = \frac{s}{s^2 - a^2} \quad (s > |a|)$

PROOFS :

(1) $L\{1\} = \int_0^\infty e^{-st} \cdot 1 \cdot dt = \left[\frac{e^{-st}}{-s} \right]_0^\infty = \frac{1}{s}, \text{ if } s > 0$

(2) $L\{t^n\} = \int_0^\infty e^{-st} \cdot t^n \cdot dt = \int_0^\infty e^{-p} \cdot \frac{p^{n-1}}{s} \cdot dp$, on putting $st = p$

$$\frac{1}{s} \int_0^\infty e^{-p} \cdot p^{n-1} dp$$

$$\frac{(n-1)!}{s^n}, \text{ if } n > -1 \text{ and } s > 0$$

S_{n-1}

If n is a positive integer, $F(n+1) = n!$. Therefore, $L\{t^n\} = \frac{n!}{s^{n+1}}, \text{ if } s > 0$

(3) $L\{e^{at}\} = \int_0^\infty e^{-st} \cdot e^{at} dt = \int_0^\infty e^{-(s-a)t} dt = \left[\frac{e^{-(s-a)t}}{-(s-a)} \right]_0^\infty = \frac{1}{s-a}, \text{ if } s > a$

(4) $L\{\sin at\} = \int_0^\infty e^{-st} \sin at dt = \int_0^\infty \frac{2e^{-st}}{s^2 + a^2} (s \sin at - a \cos at) dt = \frac{a}{s^2 + a^2}, \text{ if } s > 0$

(5) $L\{\cos at\} = \int_0^\infty e^{-st} \cos at dt = \int_0^\infty \frac{e^{-st}}{s^2 + a^2} (s \cos at + a \sin at) dt = \frac{s}{s^2 + a^2}, \text{ if } s > 0$

(6) $L\{\sinh at\} = \int_0^\infty e^{-st} \sinh at dt = \frac{1}{2} \int_0^\infty (e^{st} - e^{-st}) dt = \frac{1}{2} \left[\frac{e^{st}}{s} - \frac{e^{-st}}{-s} \right]_0^\infty = \frac{1}{s^2 - a^2}, \text{ for } s > |a|$

(7) $L\{\cosh at\} = \int_0^\infty e^{-st} \cosh at dt = \frac{1}{2} \int_0^\infty (e^{st} + e^{-st}) dt = \frac{1}{2} \left[\frac{e^{st}}{s} + \frac{e^{-st}}{-s} \right]_0^\infty = \frac{s}{s^2 - a^2}, \text{ for } s > |a|$

$\frac{1}{s^2 - a^2}, \text{ for } s > |a|$

Engineering Mathematics – III

27

PROPERTIES OF LAPLACE TRANSFORMS :

1. LINEARITY PROPERTY :

If a, b, c be any constants and f, g, h any functions of t, then

$$L\{af(t) + bg(t) - ch(t)\} = aL\{f(t)\} + bL\{g(t)\} - cL\{h(t)\}$$

By definition,

$$L.H.S = \int_0^{\infty} e^{-st} [af(t) + bg(t) - ch(t)] dt$$

$$\begin{aligned} &= \int_0^{\infty} a e^{-st} f(t) dt + \int_0^{\infty} b e^{-st} g(t) dt - \int_0^{\infty} c e^{-st} h(t) dt \\ &= aL\{f(t)\} + bL\{g(t)\} - cL\{h(t)\} \end{aligned}$$

II. FIRST SHIFTING PROPERTY :

If $L\{f(t)\} = \bar{f}(s)$, then

$$L\{e^{at} f(t)\} = \bar{f}(s - a)$$

By definition,

$$L\{e^{at} f(t)\} = \int_0^{\infty} e^{-st} e^{at} f(t) dt = \int_0^{\infty} e^{-(s-a)t} f(t) dt$$

$$= \int_0^{\infty} e^{-rt} f(t) dt, \text{ where } r = s - a \quad \bar{f}(r) = \bar{f}(s - a).$$

APPLICATION OF FIRST SHIFTING PROPERTY :

$$(1) \quad L\{e^{at}\} = \frac{1}{s - a}$$

$$(2) \quad L\{e^{at} t^n\} = \frac{n!}{(s - a)^{n+1}} \text{ when } n = 1, 2, 3, \dots$$

$$(3) \quad L\{e^{at} \sin bt\} = \frac{b}{(s - a)^2 + b^2}$$

$$(4) \quad L\{e^{at} \cos bt\} = \frac{s - a}{(s - a)^2 + b^2}$$

$$(5) \quad L\{e^{at} \sinh bt\} = \frac{b}{(s - a)^2 - b^2}$$

$$(6) \quad L\{e^{at} \cosh bt\} = \frac{s - a}{(s - a)^2 - b^2}$$

where in each case $s > a$.

28

Engineering Mathematics – III

III. CHANGE OF SCALE PROPERTY :If $L\{f(t)\} = f(s)$, then

$$L\{f(at)\} = \frac{1}{a} f\left(\frac{s}{a}\right)$$

By definition,

$$L\{f(at)\} = \int_0^{\infty} e^{-st} f(at) dt$$

$$= \int_0^{\infty} e^{-su/a} f(u) \frac{du}{a} \quad [\text{put } at = u \text{ then } dt = \frac{du}{a}]$$

$$= \frac{1}{a} \int_0^{\infty} e^{-su/a} f(u) du = \frac{1}{a} f\left(\frac{s}{a}\right)$$

Example – 3 :Find the Laplace transform of $e^{2t}(3t^5 - \cos 4t)$.**Solution :**

$$L\{e^{2t}(3t^5 - \cos 4t)\}$$

$$= 3L\{e^{2t}t^5\} - L\{e^{2t}\cos 4t\}$$

$$\frac{3 \cdot 5!}{(s-2)^6} - \frac{360}{(s-2)^6} - \frac{s^2}{(s-2)^2} - \frac{4s}{(s-2)^2}$$

Example – 4 :Find the Laplace transform of $e^{-t} \sin^2 3t$ **Solution :**

$$\text{We have } L\{\sin^2 3t\} = \frac{1}{2} L\{1 - \cos 6t\} = \frac{1}{2} \left[\frac{1}{s} - \frac{s}{s^2 - 36} \right] = \frac{1}{2} \left[\frac{s(s-36) - s^2}{s^2(s-36)} \right] = \frac{1}{2} \left[\frac{-s^2 + 36s}{s^2(s-36)} \right] = \frac{1}{2} \left[\frac{s(36-s)}{s^2(s-36)} \right] = \frac{1}{2} \left[\frac{-s}{s^2} \right] = -\frac{1}{2s}$$

Example – 5 :Find the Laplace transform of $e^{-3t} \sin 5t \sin 3t$.**Solution :**

$$\text{We have, } L\{\sin 5t \sin 3t\} = \frac{1}{2} L\{\cos 2t - \cos 8t\}$$

$$\frac{1}{2} \left[\frac{s}{s^2 - 4} - \frac{s}{s^2 - 64} \right] = \frac{1}{2} \left[\frac{30s}{(s^2 - 4)(s^2 - 64)} \right] = f(s)$$

By first shifting property, we get

$$L\{e^{-3t} \sin 5t \sin 3t\} = \frac{1}{(s+3)^2 - 4} \frac{1}{(s+3)^2 - 64} \frac{1}{(s+3)^2 - 36}$$

$$30(s+3)$$

$$30(s+3)$$

Example – 6 : $\frac{1}{(s-3)^2 - 4} \frac{1}{(s-3)^2 - 64} \frac{1}{(s-3)^2 - 36}$

Find the laplace transform of $e^{-2t} (2\sqrt{t} - 3/\sqrt{t})$

Solution :

We have

$$L\{2\sqrt{t} - 3/\sqrt{t}\} = 2L\sqrt{t} - 3L\frac{1}{\sqrt{t}} = \frac{2 \cdot \frac{1}{2} \Gamma(\frac{1}{2})}{s^{\frac{3}{2}}} - \frac{3 \cdot \frac{1}{2} \Gamma(\frac{1}{2})}{s^{\frac{1}{2}}} = \frac{\sqrt{3}}{s^{\frac{3}{2}}} - \frac{\sqrt{3}}{s^{\frac{1}{2}}}$$

By first shifting property, we get $\frac{\sqrt{3}}{(s+2)^{\frac{3}{2}}} - \frac{\sqrt{3}}{(s+2)^{\frac{1}{2}}}$

$$L\{e^{-2t} (2\sqrt{t} - 3/\sqrt{t})\} = \frac{\sqrt{3}}{(s+2)^{\frac{3}{2}}} - \frac{\sqrt{3}}{(s+2)^{\frac{1}{2}}}$$

Example – 7 :

$$L\frac{\sin at}{t} = L\frac{\sin t}{t} \tan^{-1} \frac{1}{s}$$

Solution :

Given that, $L\frac{\sin at}{t} = \tan^{-1} \frac{1}{s+a}$

By change of scale property, we get

$$L\frac{\sin at}{at} = \frac{1}{a} \tan^{-1} \frac{1}{s/a} = \frac{1}{a} \tan^{-1} \frac{a}{s}$$

$$L\frac{\sin at}{t} = \tan^{-1} \frac{a}{s}$$

Therefore, $L\frac{\sin at}{t} = \tan^{-1} \frac{a}{s}$

30

Engineering Mathematics – III

LAPLACE TRANSFORMS OF DERIVATIVES :

(1) $f'(t)$ be continuous and $L\{f(t)\} = f(s)$, then $L\{f'(t)\} = sf(s) - f(0)$.
Proof : We have

$$L\{f'(t)\} = \int_0^{\infty} e^{-st} f'(t) dt = s \int_0^{\infty} e^{-st} f(t) dt - f(0)$$

Now assuming $f(t)$ be such that $\lim_{t \rightarrow \infty} e^{-st} f(t) = 0$, we have

$$L\{f'(t)\} = sf(s) - f(0)$$

Thus, $L\{f'(t)\} = sf(s) - f(0)$

(2) If $f'(t)$ and its first $(n - 1)$ derivatives be continuous, then

$$L\{f^{(n)}(t)\} = s^n f(s) - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - f^{(n-1)}(0)$$

Thus,

$$L\{f''(t)\} = s^2 f(s) - sf(0) - f'(0)$$

$$L\{f'''(t)\} = s^3 f(s) - s^2 f(0) - sf'(0) - f''(0)$$

$$L\{f^{(iv)}(t)\} = s^4 f(s) - s^3 f(0) - s^2 f'(0) - sf''(0) - f^{(3)}(0)$$

and so on.

Laplace transforms of integrals :

$$\text{If } L\{f(t)\} = f(s), \text{ then } L\left\{\int_0^t f(u) du\right\} = \frac{1}{s} f(s)$$

Proof :

$$\text{Let } \phi(t) = \int_0^t f(u) du, \text{ then } \phi'(t) = f(t) \text{ and } \phi(0) = 0$$

$$L\{\phi'(t)\} = s\phi(s) - \phi(0)$$

$$\text{or } L\{f(t)\} = s\phi(s)$$

$$\text{or } \phi(s) = \frac{1}{s} f(s)$$

$$\text{or } \phi(s) = \frac{1}{s} f(s)$$

$$\text{Hence, } L\left\{\int_0^t f(u) du\right\} = \frac{1}{s} f(s)$$

$$\phi(s) = \frac{1}{s} f(s)$$

Engineering Mathematics – III

31

Multiplication By t^n :If $L\{f(t)\} = \bar{f}(s)$, then

$$L\{t^n f(t)\} = (-1)^n \bar{f}^{(n)}(s) \quad -$$

Division By t : $\int ds \bar{f}(s)$, where $n = 1, 2, 3, \dots$ If $L\{f(t)\} = \bar{f}(s)$, then

$$L\left\{\frac{f(t)}{t}\right\} = \int_s^{\infty} \bar{f}(s) ds, \text{ provided the integral exists.}$$

Example –8 :

Find the laplace transforms of

(1) $t \sin at$ (2) $t \cos at$

Solution :

(1) We have, $L\{\sin at\} = \frac{a}{s^2 + a^2}$

$$L\{t \sin at\} = \frac{d}{ds} \frac{a}{s^2 + a^2} = \frac{-2as}{(s^2 + a^2)^2}$$

$$\text{Hence } L\{t \sin at\} = \frac{2as}{(s^2 + a^2)^2}$$

(2) We have, $L\{\cos at\} = \frac{s}{s^2 + a^2}$

$$L\{t \cos at\} = \frac{d}{ds} \frac{s}{s^2 + a^2} = \frac{s^2 + a^2 - 2s^2}{(s^2 + a^2)^2}$$

$$\text{Hence, } L\{t \cos at\} = \frac{s^2 - a^2}{(s^2 + a^2)^2}$$

Example – 9 :

Find the laplace transforms of $t^2 \cos at$.

Solution :

We have, $L\{\cos at\} = \frac{s}{s^2 + a^2}$

$$L\{t^2 \cos at\} = \frac{d^2}{ds^2} \frac{s}{s^2 + a^2}$$

$$= \frac{2s^2 - 2s^2 - a^2}{(s^2 + a^2)^3}$$

32

Engineering Mathematics – III

$$\frac{d}{ds} \frac{a_2 s^2}{(s^2 - a^2)^2}$$

$$\frac{2s(s^2 - a^2)^2 - 2(a_2 s^2) \cdot 2s(s^2 - a^2)}{(s^2 - a^2)^4}$$

$$\frac{2s(s^2 - a^2) - 4s(s^2 - a^2) + 2s(3a^2)}{(s^2 - a^2)^3}$$

Example – 10 :

Find the laplace transforms of $(e^{at} - e^{bt})$.

Solution :

We have, $L \{ e^{-at} - e^{-bt} \} = \frac{1}{(s-a)} - \frac{1}{(s-b)}$

$$L \{ e^{at} - e^{bt} \} = \frac{1}{s-a} - \frac{1}{s-b}$$

$$\log \frac{s-a}{s} - \log \frac{s-b}{s}$$

$$\log \frac{s-a}{s} - \log \frac{s(1-b/s)}{s}$$

$$\log 1 - \log \frac{s-a}{s}$$

$$\log \frac{s-a}{s} - \log \frac{s-b}{s}$$

Example – 11 :

Find the inverse Laplace transform of $\frac{e^{at} \cos bt}{t}$

Solution :

We have, $L \{ \frac{e^{at} \cos bt}{t} \} = \int_a^{\infty} \frac{1}{s^2 - b^2} ds$

$$L \{ \frac{e^{at} \cos bt}{t} \} = \int_a^{\infty} \frac{1}{s^2 - b^2} ds$$

$$L \{ \frac{e^{at} \cos bt}{t} \} = \frac{1}{s-a} - \frac{1}{s-b}$$

Engineering Mathematics – III

33

$$\log s = a + \frac{1}{2} \log s^2 = \log \frac{b^2}{s}$$

$$\frac{1}{2} \log s = a + \log \frac{b^2}{s^2}$$

$$\frac{1}{2} \log \frac{s^2}{b^2} = \frac{s a}{s^2 b^2}$$

$$\frac{1}{2} \log \frac{s^2}{b^2} = \frac{s a}{s^2 b^2}$$

$$\frac{1}{2} \log \frac{s^2}{b^2} = \frac{s a}{s^2 b^2}$$

$$\frac{1}{2} \log \frac{s^2}{b^2} = \frac{s a}{s^2 b^2}$$

$$\frac{1}{2} \log \frac{s^2}{b^2} = \frac{s a}{s^2 b^2}$$

$$\frac{1}{2} \log \frac{s^2}{b^2} = \frac{s a}{s^2 b^2}$$

INVERSE LAPLACE TRANSFORMS :

We know that if $\{f(t)\} = f^{-1}(s)$, then $L^{-1}\{f^{-1}(s)\} = f(t)$

Let us now determine the inverse Laplace transforms of some given function of s .

- (1) $L^{-1} \frac{1}{s-1}$
- (2) $L^{-1} \frac{1}{s-a} e^{at}$
- (3) $L^{-1} \frac{1}{s^n} = \frac{t^{n-1}}{(n-1)!}$, $n = 1, 2, 3, \dots$
- (4) $L^{-1} \frac{1}{(s-a)^n} = \frac{e^{at} t^{n-1}}{(n-1)!}$, $n = 1, 2, 3, \dots$
- (5) $L^{-1} \frac{1}{s^2 + a^2} = \frac{1}{a} \sin at$
- (6) $L^{-1} \frac{1}{s^2 - a^2} = \frac{1}{2a} \sinh at$
- (7) $L^{-1} \frac{1}{s^2 + a^2} = \frac{1}{a} \cos at$

34

Engineering Mathematics – III

$$(8) \quad L^{-1} \left\{ \frac{s}{s^2 + a^2} \right\} = \cosh at$$

$$L^{-1} \left\{ \frac{1}{s^2 + a^2} \right\} = \frac{1}{a} e^{at} \sin bt$$

$$(9) \quad L^{-1} \left\{ \frac{b}{(s-a)^2 + b^2} \right\} = e^{at} \cos bt$$

$$(10) \quad L^{-1} \left\{ \frac{b}{(s-a)^2 + b^2} \right\} = e^{at} \sin bt$$

$$(11) \quad L^{-1} \left\{ \frac{s}{(s^2 + a^2)^2} \right\} = \frac{1}{2a} t \sin at$$

$$L^{-1} \left\{ \frac{1}{(s^2 + a^2)^2} \right\} = \frac{1}{2a} (\sin at - at \cos at)$$

$$(12) \quad L^{-1} \left\{ \frac{1}{(s^2 + a^2)^2} \right\} = \frac{1}{2a^3} (\sin at - at \cos at)$$

INVERSE LAPLACE TRANSFORMS BY THE METHOD OF PARTIAL FRACTIONS :

We have seen that $L\{f(t)\}$ in many cases, is a rational algebraic function of s . Hence to find the inverse laplace transforms of $f(s)$, we first express the given function of s into partial fractions which will, then, be recognizable as one of the above mentioned standard forms.

Example – 12:

$$s^2 + s + 2$$

Find the inverse laplace transform of $\frac{s^2 + s + 2}{(s-1)^2(s-3)}$.

Solution :

Suppose that,

$$\frac{s^2 + s + 2}{(s-1)^2(s-3)} = \frac{A}{(s-1)} + \frac{B}{(s-1)^2} + \frac{C}{(s-3)} \dots\dots\dots (1)$$

Multiplying both sides of (1) by $(s-1)^2(s-3)$, we get

$$s^2 + s + 2 = A(s-1)(s-3) + B(s-3) + C(s-1)^2 \dots\dots\dots (2)$$

Putting $s = -1$ 1

$$2 = -4B \rightarrow B = -\frac{1}{2}$$

Putting $s = 3$

$$14 = 16C \rightarrow C = \frac{7}{8}$$

Equating co-efficient of s^2 , we get

$$1 = A + C \rightarrow A = 1 - C \rightarrow A = \frac{1}{8}$$

Engineering Mathematics – III

Putting the values of A, B, C in (1) we get

$$L^{-1} \left\{ \frac{s^2 s}{(s-1)^2 (s-3)} \right\} = \frac{1}{8} \frac{1}{(s-1)} + \frac{1}{2} \frac{1}{(s-1)^2} + \frac{7}{8} \frac{1}{(s-3)}$$

$$= \frac{1}{8} e^t + \frac{1}{2} t e^t + \frac{7}{8} e^{3t}$$

Example – 13 :

Find the inverse laplace transforms of $\frac{s}{(s-2)(s+9)}$

Solution : Suppose that,

$$\frac{s}{(s-2)(s+9)} = \frac{A}{s-2} + \frac{Bs+C}{s+9} \quad \dots(1)$$

Multiplying both sides by $(s-2)(s+9)$, we get

$$s = A(s+9) + (Bs+C)(s-2) \quad \dots(2)$$

Putting $s = 2, 2 = 13A \rightarrow A = \frac{2}{13}$

Putting $s = 0, 0 = 9A - 2c \rightarrow C = \frac{9}{13}$

Equating co-efficient of s^2 , we get

$$0 = A + B \rightarrow B = -\frac{2}{13}$$

Putting the values of A, B, C in (1), we get

$$L^{-1} \left\{ \frac{s}{(s-2)(s+9)} \right\} = \frac{2}{13} \frac{1}{s-2} - \frac{2}{13} \frac{s}{s+9} + \frac{9}{13} \frac{1}{s+9}$$

$$= \frac{2}{13} e^{2t} - \frac{2}{13} \cos 3t + \frac{9}{13} \sin 3t$$

OTHER METHODS OF FINDING INVERSE LAPLACE TRANSFORMS :

(I) SHIFTING PROPERTY :

If $L^{-1} \{ \bar{f}(s) \} = f(t)$, then

$$L^{-1} \{ \bar{f}(s - a) \} = e^{at} f(t) = e^{at} L^{-1} \{ \bar{f}(s) \}$$

(II) If $L^{-1} \{ \bar{f}(s) \} = f(t)$ and $f(0) = 0$, then $L^{-1} \{ s \bar{f}(s) \} = \frac{d}{dt} f(t)$.

In general, $L^{-1} \{ s^n \bar{f}(s) \} = \frac{d^n}{dt^n} \{ f(t) \}$,

Provided $f(0) = f'(0) = \dots = f^{(n-1)}(0) = 0$.

(III) If $L^{-1} \{ \bar{f}(s) \} = f(t)$, then $L^{-1} \left\{ \frac{\bar{f}(s)}{s} \right\} = \int_0^t f(t - \tau) d\tau$

(IV) $L^{-1} \left\{ \frac{\bar{f}(s)}{s - a} \right\} = f(t) e^{at}$, then $t \cdot f(t) = L^{-1} \left\{ \frac{d \bar{f}(s)}{ds} \right\}$

(V) If $f(t) = L^{-1} \{ \bar{f}(s) \}$, then $L^{-1} \left\{ \frac{f(t)}{t} \right\} = \int_s^\infty \bar{f}(s) ds$.

This formula is useful in finding $f(t)$ when $\bar{f}(s)$ is given.

Example – 14 :

Find the inverse Laplace transform of $\tan^{-1} \frac{2}{s}$.

Solution :-

Let $L^{-1} \left\{ \frac{2}{s} \right\} = f(t)$

$$\rightarrow L\{f(t)\} = \tan^{-1} \frac{2f}{s}$$

Then by formula IV we get,

$$L\{t \cdot f(t)\} = \frac{d}{ds} \tan^{-1} \frac{2f}{s}$$

$$= \frac{1}{2/s^2} \cdot \frac{2}{s^2}$$

$$\frac{2}{s^2} = 4$$

Engineering Mathematics – III

$$\rightarrow f(t) = L^{-1} \left\{ \frac{2 \sin 2t}{s^2 + 4} \right\}$$

$$\rightarrow f(t) = \frac{\sin 2t}{2}$$

$$\rightarrow f(t) = \frac{1}{2} \sin 2t$$

$$\therefore L^{-1} \left\{ \frac{2 \sin 2t}{s^2 + 4} \right\} = \frac{1}{2} \sin 2t$$

Example – 16 :

Find the inverse Laplace transform of $\log \frac{s}{s-1}$.

Solution :- Let $f(t) = L^{-1} \left\{ \log \frac{s}{s-1} \right\}$

$$\rightarrow L \{t f(t)\} = - \frac{d}{ds} \log \frac{s}{s-1}$$

Then by formula IV we get,

$$L \{t \cdot f(t)\} = - \frac{d}{ds} \log \frac{s}{s-1} = - \frac{d}{ds} (\log s - \log (s-1))$$

$$= - \left(\frac{1}{s} - \frac{1}{s-1} \right) = \frac{1}{s-1} - \frac{1}{s}$$

$$\rightarrow t \cdot f(t) = L^{-1} \left\{ \frac{1}{s-1} - \frac{1}{s} \right\}$$

$$\rightarrow f(t) = \frac{e^t - 1}{t}$$

$$\therefore L^{-1} \left\{ \log \frac{s}{s-1} \right\} = \frac{e^t - 1}{t}$$

Example – 17 :

Find the inverse Laplace transform of $\frac{1}{s^2 + a^2}$.

Solution :

We have

$$L^{-1} \left\{ \frac{1}{s^2 + a^2} \right\} = \frac{1}{a} \sin at = f(t).$$

38

Engineering Mathematics – III

Then by Formula III we get,

$$L^{-1} \frac{1}{s^2 + a^2} = \frac{1}{a} \int_0^t \sin at \, dt = \frac{1}{a} \left[-\frac{1}{a} \cos at \right]_0^t = \frac{1}{a^2} (1 - \cos at)$$

Thus we have,

$$L^{-1} \frac{1}{s^2 + a^2} = \frac{1}{a^2} (1 - \cos at)$$

Example – 18 :

Find the inverse Laplace transform of $\frac{1}{s^2 - s - 5}$.

Solution : $L^{-1} \left\{ \frac{1}{s^2 - s - 5} \right\} = f(t)$

We have, $L^{-1} \left\{ \frac{1}{s^2 - s - 5} \right\} = f(t)$

Then by Formula III, we get

$$L^{-1} \left\{ \frac{1}{s^2 - s - 5} \right\} = \int_0^t e^{5t} \, dt$$

$$L^{-1} \left\{ \frac{1}{s^2 - s - 5} \right\} = \frac{1}{5} \int_0^t e^{5t} \, dt = \frac{1}{5} \left[\frac{e^{5t}}{5} \right]_0^t = \frac{1}{25} (e^{5t} - 1)$$

Thus we have,

$$L^{-1} \left\{ \frac{1}{s^2 - s - 5} \right\} = \frac{1}{25} (e^{5t} - 1)$$

Engineering Mathematics – III

39

$$\frac{1}{s} + \frac{t}{s^2} + \frac{e^{5t}}{s} - \frac{1}{s}$$

$$\frac{1}{s} + \frac{t}{s^2} + \frac{5t}{s} - \frac{1}{s}$$

Example – 19 : 25

$$\frac{a^2}{s^2}$$

Solution :

We have,

$$\frac{s^2}{s^2 - a^2} = \frac{1}{2} \frac{d}{dt} \sin at + f(t)$$

Since $f(0) = 0$, we get from Formula II that,

$$L^{-1} \left\{ \frac{s^2}{s^2 - a^2} \right\} = L^{-1} \left\{ \frac{1}{2} \frac{d}{dt} \sin at + f(t) \right\}$$

$$\frac{d}{dt} \left(\frac{1}{2} t \sin at \right)$$

$$\frac{1}{2} a (\sin at + at \cos at)$$

Example –20 :

Find the inverse Laplace transform of $\frac{s-3}{s^2-6s+13}$

Solution :

$$\text{We have, } \frac{s-3}{s^2-6s+13} = \frac{s-3}{s^2-6s+9+4} = \frac{s-3}{(s-3)^2+2^2}$$

Then by formula I we get

$$L^{-1} \left\{ \frac{s-3}{(s-3)^2+2^2} \right\} = e^{3t} L^{-1} \left\{ \frac{s-2}{s^2+2^2} \right\}$$

$$\frac{1}{2} e^{3t} \cdot t \sin 2t.$$

4

40

Engineering Mathematics – III

Example – 21 :

s

Find the inverse Laplace transform of $\frac{s}{s^2 + a^2}$.

Solution :

$$\text{Let, } f(t) = L^{-1} \frac{s}{s^2 + a^2}$$

Then by formula V we get

$$L^{-1} \left\{ \frac{f(s)}{s} \right\} = \int_0^t f(s) ds$$

$$\begin{aligned} \therefore L^{-1} \left\{ \frac{s}{s^2 + a^2} \right\} &= \int_0^t \frac{1}{s^2 + a^2} ds \\ &= \frac{1}{a} \int_0^t \frac{1}{\left(\frac{s}{a}\right)^2 + 1} \cdot \frac{1}{a} ds \\ &= \frac{1}{2a} \int_0^t \frac{2s}{s^2 + a^2} ds \\ &= \frac{1}{2a} \int_0^t \frac{d(s^2 + a^2)}{s^2 + a^2} \\ &= \frac{1}{2a} \left[\ln |s^2 + a^2| \right]_0^t \end{aligned}$$

$$\text{Hence } f(t) = L^{-1} \left\{ \frac{s}{s^2 + a^2} \right\} = \frac{1}{2a} \ln |s^2 + a^2|$$

LAPLACE TRANSFORM METHOD TO SOLVE LINEAR DIFFERENTIAL EQUATIONS WITH CONSTANT COEFFICIENTS ASSOCIATED WITH INITIAL CONDITIONS :

Linear differential equations with constant coefficients associated with initial conditions can be easily solved by Laplace transform method.

Working Procedure :

Step - 1 : Take the Laplace transform of both sides of the differential equation and then put the given initial conditions.

Step - 2 : Transpose the terms with minus signs to the right.

Step - 3 : Divide by the co-efficient of y , getting y as a known function of s .

Step - 5 : Resolve this function of s into partial fractions.

Step - 5 : Take the inverse Laplace transform of both sides. This gives y as a

function of t which is the desired solution satisfying the given conditions.

Engineering Mathematics – III

41

Example – 22 :

Solve the following equation by transform method;

$$y'' - 3y' + 2y = e^{3t}, \text{ when } y(0) = 1 \text{ and } y'(0) = 0.$$

Solution :

$$\text{We have, } y'' - 3y' + 2y = e^{3t} \quad \dots(1)$$

Taking Laplace transform of both sides of (1), we get

$$L\{y''\} = 3L\{y'\} + 2L\{y\} = L\{e^{3t}\}$$

$$\rightarrow [s^2 \bar{y} - sy(0) - y'(0)] - 3[s\bar{y} - y(0)] + 2\bar{y} = \frac{1}{s-3}$$

Putting $y(0) = 1$ and $y'(0) = 0$, we get

$$s^2 \bar{y} - s - 3s\bar{y} + 3 + 2\bar{y} = \frac{1}{s-3}$$

$$\rightarrow \bar{y} \cdot (s^2 - 3s + 2) = \frac{1}{s-3} + s - 3$$

$$\rightarrow \bar{y} = \frac{s^2 - 6s + 10}{(s-3)(s-1)(s-2)}$$

$$\rightarrow \bar{y} = \frac{s^2 - 6s + 10}{(s-3)(s-1)(s-2)} = \frac{A}{s-3} + \frac{B}{s-1} + \frac{C}{s-2} \quad \dots(2)$$

$$\text{Let, } \frac{s^2 - 6s + 10}{(s-3)(s-1)(s-2)} = \frac{A}{s-3} + \frac{B}{s-1} + \frac{C}{s-2}$$

Multiplying both sides of (3) by $(s-3)(s-1)(s-2)$, we get

$$s^2 - 6s + 10 = A(s-1)(s-2) + B(s-3)(s-2) + C(s-3)(s-1) \quad \dots(4)$$

$$\text{Putting } s = 1, B = \frac{5}{2}$$

$$\text{Putting } s = 2, C = -2$$

$$\text{Putting } s = 3, A = \frac{1}{2}$$

Substituting the values of A, B, C in (3), we get

$$\bar{y} = \frac{1}{2} \frac{1}{s-3} + \frac{5}{2} \frac{1}{s-1} - \frac{2}{s-2}$$

Taking inverse Laplace transform of both sides, we get

$$L^{-1}\{\bar{y}\} = \frac{1}{2} L^{-1}\left\{\frac{1}{s-3}\right\} + \frac{5}{2} L^{-1}\left\{\frac{1}{s-1}\right\} - 2 L^{-1}\left\{\frac{1}{s-2}\right\}$$

$$\therefore y = \frac{1}{2} e^{3t} + \frac{5}{2} e^t - 2e^{2t}$$

42

Engineering Mathematics – III

Example – 23 :

Solve the following equation by transform method;

$$(D^2 + \omega^2)y = \cos \omega t, t > 0, \text{ given that } y = 0 \text{ and } Dy = 0 \text{ at } t = 0$$

Solution :

We have

$$(D^2 + \omega^2)y = \cos \omega t$$

$$\text{i.e., } y'' + \omega^2 y = \cos \omega t, \text{ given } y(0) = y'(0) = 0$$

Taking Laplace transform of both sides of (1), we get

$$L\{y''\} + \omega^2 L\{y\} = L\{\cos \omega t\}$$

$$\rightarrow s^2 y - sy(0) - y'(0) + \omega^2 y = \frac{s}{s^2 + \omega^2}$$

Putting $y(0) = 0$ and $y'(0) = 0$, we get

$$y \cdot (s^2 + \omega^2) = \frac{s}{s^2 + \omega^2}$$

$$\rightarrow y = \frac{s}{s^2 + \omega^2} \dots(2)$$

Taking inverse Laplace transform, we get

$$y = \frac{1}{\omega} \sin \omega t$$

$$y = \frac{1}{\omega} \sin \omega t$$

This is the required solution.

Assignment

- Find the Laplace transforms of the following :
 - $\int_0^t \sin t \, dt$
 - $\int_0^t e^{-t} \cos t \, dt$
- Find the Laplace Transform of $f(t)$ in each of the following :
 - $\sin 2t$, when $0 < t < 2$
 - $f(t) = \begin{cases} 1, & \text{when } 0 < t < 2 \\ t, & \text{when } t > 2 \end{cases}$
- Obtain the inverse Laplace transforms of the following functions
 - $\frac{2s^2 + 6s + 5}{s^3 + 6s^2 + 11s + 6}$
 - $a(s^2 + 2a^2)$
 - $\frac{s}{s^2 + 6s + 13}$
 - $\log \frac{4a^4}{s^4 - 1}$



CHAPTER – 4

FOURIER SERIES

Periodic Functions :

If the value of each ordinate $f(t)$ repeat it self at equal interval in the abscissa, then $f(t)$ is said to be a periodic function.

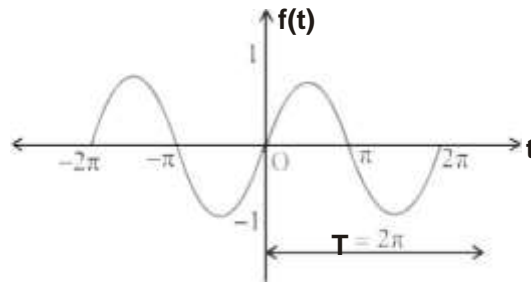
If $f(t) = f(t + T) = f(t + 2T) = \dots$, then

T is called period of the function $f(t)$.

For example

$$\sin x = \sin(x + 2\pi) = \sin(x + 4\pi) = \dots$$

So $\sin x$ is called a periodic function of period 2π



Founier Series :

A series of sines and cosines of an angle and its multiple of the form

$$a_0 + a_1 \cos x + a_2 \cos 2x + \dots + a_n \cos nx + \dots$$

$$+ b_1 \sin x + b_2 \sin 2x + \dots + b_n \sin nx + \dots$$

$$\frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos nx + b_n \sin nx)$$

is called a fouries series, there a_0 , a_n & b_n are called fourier constants

Useful Integrals

The following integrals are useful in Fourier series :

1. $\int_0^{2\pi} \sin nx \, dx = 0$

2. $\int_0^{2\pi} \cos nx \, dx = 0$

44

Engineering Mathematics – III

3. $\int \sin^2 nx dx$ 4. $\int \cos^2 nx dx$

5. $\int \sin nx \cdot \sin mx dx = 0$ 6. $\int \cos nx \cdot \cos mx dx = 0$

7. $\int \sin nx \cdot \cos mx dx = 0$ 8. $\int \sin nx \cdot \cos nx dx = 0$

9. $uv = uv_1 + u v_2 + u v_3 + \dots$

where $v_1 = \int v dx$, $v_2 = \int v_1 dx$, $v_3 = \int v_2 dx$ $u = \frac{du}{dx}$, $u = \frac{d^2u}{dx^2}$ &

10. $\sin n\pi = 0$ & $\cos n\pi = (-1)^n$ where $n \in \mathbb{I}$
 Let $f(x)$ be represented in the interval $(\alpha, \alpha + 2\pi)$ by fourier series

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos nx + \sum_{n=1}^{\infty} b_n \sin nx$$

To find a_0 : $\int_{\alpha}^{\alpha+2\pi} f(x) dx = \int_{\alpha}^{\alpha+2\pi} \left[\frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos nx + \sum_{n=1}^{\infty} b_n \sin nx \right] dx \dots(1)$

Integrate both sides of equation (1) from $x = \alpha$ to $x = \alpha + 2\pi$. Then

$$\int_{\alpha}^{\alpha+2\pi} f(x) dx = \int_{\alpha}^{\alpha+2\pi} \frac{a_0}{2} dx + \sum_{n=1}^{\infty} a_n \int_{\alpha}^{\alpha+2\pi} \cos nx dx + \sum_{n=1}^{\infty} b_n \int_{\alpha}^{\alpha+2\pi} \sin nx dx$$

Hence $a_0 = \frac{1}{2} \int_{\alpha}^{\alpha+2\pi} f(x) dx$ $\frac{1}{2} a_0 (2\pi) = a_0 \pi$

To find a_n : Multiply $\cos nx$ on both sides of equation (1) and integrate from $x = \alpha$ to $x = \alpha + 2\pi$. Then

$$\int_{\alpha}^{\alpha+2\pi} f(x) \cos nx dx = \int_{\alpha}^{\alpha+2\pi} \left[\frac{a_0}{2} \cos nx + \sum_{n=1}^{\infty} a_n \cos nx \cos nx + \sum_{n=1}^{\infty} b_n \sin nx \cos nx \right] dx = 0 + \pi a_n + 0$$

To find b_n : Multiply $\sin nx$ on both sides of equation (1) and integrate from $x = \alpha$ to $x = \alpha + 2\pi$, then

$$\int_{\alpha}^{\alpha+2\pi} f(x) \sin nx dx = \int_{\alpha}^{\alpha+2\pi} \left[\frac{a_0}{2} \sin nx + \sum_{n=1}^{\infty} a_n \cos nx \sin nx + \sum_{n=1}^{\infty} b_n \sin nx \sin nx \right] dx = 0 + 0 + \pi b_n$$

Engineering Mathematics – III

Hence $a_n = \frac{1}{2} \int_a^b f(x) \sin nx dx$

Making $\alpha = 0$, the interval becomes $0 < x < \pi$ and the formula (1) reduces to
 $a_n = \frac{1}{\pi} \int_0^\pi f(x) \cos nx dx$

$$a_n = \frac{1}{\pi} \int_0^\pi f(x) \cos nx dx \quad \dots(ii)$$

$$b_n = \frac{1}{\pi} \int_0^\pi f(x) \sin nx dx$$

Putting $\alpha = -\pi$, The interval becomes $-\pi < x < \pi$, the formula (I) reduces to

$$a_0 = \frac{1}{2\pi} \int_{-\pi}^\pi f(x) dx$$

$$a_n = \frac{1}{\pi} \int_{-\pi}^\pi f(x) \cos nx dx$$

$$b_n = \frac{1}{\pi} \int_{-\pi}^\pi f(x) \sin nx dx \dots (iii)$$

Euler's Formula :

$f(x)$ in the interval $\pi < x < \pi + 2\pi$ is given by

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos nx + \sum_{n=1}^{\infty} b_n \sin nx$$

where $a_0 = \frac{1}{2\pi} \int_a^b f(x) dx$

$$a_n = \frac{1}{\pi} \int_a^b f(x) \cos nx dx$$

$$b_n = \frac{1}{\pi} \int_a^b f(x) \sin nx dx$$

The value of a_0, a_n & b_n are known.

Euler's formula.

Example – 1 :

Given that $f(x) = x + x^2$ for $-\pi < x < \pi$, find the Fourier expansion of $f(x)$. Hence that

$$1 - \frac{1}{6} + \frac{1}{2^2} - \frac{1}{3^2} + \frac{1}{4^2} \dots$$

Solution :

$$\text{Let } x + x^2 = \sum_{n=0}^{\infty} a_n \cos nx + a_2 \cos 2x + \dots + b_1 \sin x + b_2 \sin 2x + \dots \quad (1)$$

1

$$a_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) dx = \frac{1}{2\pi} \int_{-\pi}^{\pi} (x + x^2) dx = \frac{1}{2\pi} \left[\frac{x^2}{2} + \frac{x^3}{3} \right]_{-\pi}^{\pi} = \frac{1}{2\pi} \left(\frac{\pi^2}{2} + \frac{\pi^3}{3} - \left(\frac{\pi^2}{2} + \frac{\pi^3}{3} \right) \right) = \frac{1}{2\pi} \left(\frac{\pi^2}{2} - \frac{\pi^2}{2} + \frac{\pi^3}{3} - \frac{\pi^3}{3} \right) = 0$$

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos nx dx = \frac{1}{\pi} \int_{-\pi}^{\pi} (x + x^2) \cos nx dx = \frac{1}{\pi} \left(\int_{-\pi}^{\pi} x \cos nx dx + \int_{-\pi}^{\pi} x^2 \cos nx dx \right)$$

$$= \frac{1}{\pi} \left(\frac{2x \sin nx}{n} - \frac{2 \cos nx}{n^2} + \frac{2x^2 \cos nx}{n} - \frac{4x \sin nx}{n} + \frac{4 \cos nx}{n^2} \right)_{-\pi}^{\pi} = \frac{1}{\pi} \left(\frac{2\pi \sin n\pi}{n} - \frac{2 \cos n\pi}{n^2} + \frac{2\pi^2 \cos n\pi}{n} - \frac{4\pi \sin n\pi}{n} + \frac{4 \cos n\pi}{n^2} \right)$$

$$= \frac{1}{\pi} \left(\frac{2\pi^2 \cos n\pi}{n} - \frac{2 \cos n\pi}{n^2} + \frac{4 \cos n\pi}{n^2} \right) = \frac{2 \cos n\pi}{\pi n} \left(\pi^2 + \frac{2}{n^2} \right)$$

$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin nx dx = \frac{1}{\pi} \int_{-\pi}^{\pi} (x + x^2) \sin nx dx = \frac{1}{\pi} \left(\int_{-\pi}^{\pi} x \sin nx dx + \int_{-\pi}^{\pi} x^2 \sin nx dx \right)$$

$$= \frac{1}{\pi} \left(-\frac{2x \cos nx}{n} + \frac{2 \sin nx}{n^2} - \frac{2x^2 \cos nx}{n} + \frac{4x \sin nx}{n} - \frac{4 \cos nx}{n^2} \right)_{-\pi}^{\pi} = \frac{1}{\pi} \left(-\frac{2\pi \cos n\pi}{n} + \frac{2 \sin n\pi}{n^2} - \frac{2\pi^2 \cos n\pi}{n} + \frac{4\pi \sin n\pi}{n} - \frac{4 \cos n\pi}{n^2} \right)$$

$$= \frac{1}{\pi} \left(-\frac{2\pi^2 \cos n\pi}{n} + \frac{4\pi \sin n\pi}{n} - \frac{4 \cos n\pi}{n^2} \right) = -\frac{2 \cos n\pi}{\pi n} \left(\pi^2 + \frac{2}{n^2} \right)$$

n

Substituting the values of a_0, a_n & b_n in equation (1)

2

$$x + x^2 = \frac{1}{3} \cos x - \frac{1}{2} \cos 2x + \frac{1}{3} \cos 3x - \dots + \frac{1}{2} \sin x - \frac{1}{3} \sin 2x + \frac{1}{2} \sin 3x - \dots \quad \dots(2)$$

Put $x = \pi$ in equation (2)

Engineering Mathematics – III

$$\frac{3}{2} - \frac{4}{3} + \frac{1}{2^2} - \frac{1}{3^2} + \frac{1}{4^2} - \dots \dots \dots \quad \dots(3)$$

Put $x = -\pi$ in equation (2)

$$-\pi + \pi = -\frac{1}{3} + \frac{1}{4^2} - \frac{1}{3^2} + \frac{1}{4^2} - \dots \dots \dots (4)$$

Adding equation (3) & (4)

$$\begin{aligned} & \frac{2}{3} - \frac{1}{3} + \frac{1}{2^2} - \frac{1}{3^2} + \frac{1}{4^2} - \dots \dots \dots \\ & \frac{1}{3} - \frac{1}{4^2} + \frac{1}{3^2} - \frac{1}{4^2} + \dots \dots \dots \\ & \frac{1}{3} - \frac{1}{4^2} + \frac{1}{3^2} - \frac{1}{4^2} + \dots \dots \dots \end{aligned}$$

Dirchelet's Condition :

$$a_0 + \sum_{n=1}^{\infty} (a_n \cos nx + b_n \sin nx)$$

Any function $f(x)$ can be developed as a fourier series

where a_0, a_n, b_n are constants provided.

- (i) $f(x)$ is periodic, single valued and finite
- (ii) $f(x)$ has a finite no.of discontinuities in any one period
- (iii) $f(x)$ has at most a finite no.of maxima and minima.

Discontinuous Functions : At a point of discontinuity, Fourier $f(x)$ as the arithmetic mean of left and right limits.

series gives the value of

At a point of discontinuity, $x = c$

$$f(x) = \frac{1}{2} [f(c-0) + f(c+0)]$$

Example – 2 :

Find the fourier series expansion for

$$f(x) = x, \quad 0 < x < 2\pi$$

$$f(x) = 0, \quad -\pi < x < 0$$

Deduce that $\frac{1}{1^2} - \frac{1}{3^2} + \frac{1}{5^2} - \frac{1}{7^2} + \dots = \frac{\pi^2}{12}$

Solution :

Let $f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos nx + b_n \sin nx) \dots(1)$

48

Engineering Mathematics – III

then a $\int_0^1 \cos nx dx$

$$a_n = \int_0^1 \cos nx dx = \left[\frac{\sin nx}{n} \right]_0^1 = \frac{\sin n}{n} - \frac{\sin 0}{n} = \frac{\sin n}{n}$$

$a_1 = \frac{2}{3}, a_2 = 0, a_3 = \frac{-2}{3}, a_4 = 0$

$$b_n = \int_0^1 x \sin nx dx = \left[-\frac{x \cos nx}{n} + \frac{\sin nx}{n^2} \right]_0^1 = -\frac{\cos n}{n} + \frac{\sin n}{n^2} - \left(-\frac{\cos 0}{n} + \frac{\sin 0}{n^2} \right) = \frac{1 - \cos n}{n} + \frac{\sin n}{n^2}$$

Substituting the values of a's and b's in equation (1), we get

$$f(x) = \frac{2}{3} \cos x - \frac{\cos 3x}{3} + \frac{\cos 5x}{5} - \dots + 3 \sin x - \frac{3 \sin 2x}{2} + \frac{3 \sin 3x}{3} - \dots \text{ (ii)}$$

Putting $x = 0$ in equation (ii)

$$f(0) = \frac{2}{3} - \frac{1}{3} + \frac{1}{5} - \dots \text{ (iii)}$$

Now $f(x)$ is discontinuous at $x = 0$

But $f(0 - 0) = -\pi$ and $f(0 + 0) = 0$

$$f(0) = \frac{1}{2} [f(0 - 0) + f(0 + 0)]$$

Engineering Mathematics – III

From equation (iii)

$$\frac{1}{2} - \frac{1}{4} + \frac{1}{8} - \frac{1}{16} + \frac{1}{32} - \dots$$

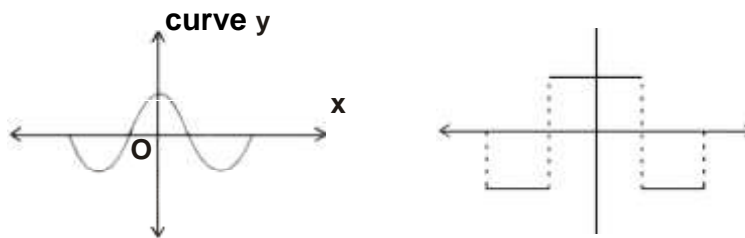
or $\frac{1}{8} - \frac{1}{4^2} + \frac{1}{3^2} - \frac{1}{5^2} + \dots$

Even Function : A function $f(x)$ is said to be even (or symmetric) function if $f(-x) = f(x)$

Ex. (i) x^2, x^4, x^6, \dots even powers of x

(ii) $\cos x, \sec x$ etc.

The graph of such a function is symmetrical with respect to y-axis. Here y-axis is a mirror for the reflection of the



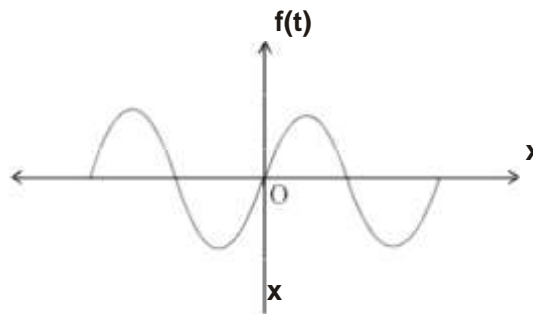
The area under such a curve from $-\pi$ to π is double the area from 0 to π .

$$\int_{-\pi}^{\pi} f(x) dx = 2 \int_0^{\pi} f(x) dx$$

Odd function : A function $f(x)$ is called odd (skew symmetric) function if $f(-x) = -f(x)$

Ex. (i) x^3, x^5, x^7, \dots odd powers of x

(ii) $\sin x, \operatorname{cosec} x, \tan x$ etc



Here the area under the curve from $-\pi$ to π is zero

i.e., $\int_{-\pi}^{\pi} f(x) dx = 0$

50

Engineering Mathematics – III

Expansion of an Even Function :

$$a_0 = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) dx$$

$$a_n = \frac{2}{\pi} \int_0^{\pi} f(x) \cos nx dx$$

As f(x) and cos nx both are even, the product of f(x).cos nx is also even.

$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin nx dx$$

As sin nx is an odd function. The product of an even function with odd function is odd. therefore we need not calculate b .

The series of an even function contain cosine terms only.

Expansion of an odd Function :

$$a_0 = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) dx = 0$$

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos nx dx = 0 \text{ (Q } f(x) \cdot \cos nx \text{ is odd function)}$$

$$b_n = \frac{2}{\pi} \int_0^{\pi} f(x) \sin nx dx$$

(Q f(x).sin nx is even function)

The series of an odd function contain sine terms only.

Example – 3 :

Obtain a fourier expansion of for f(x) = x³. in -π < x < π

Solution :

f(x) = x³ is an odd function.

a₀ = 0 and a_n = 0

$$b_n = \frac{2}{\pi} \int_0^{\pi} x^3 \sin nx dx$$

$$= \frac{2}{\pi} \left[x^3 \frac{\cos nx}{n} - 3x^2 \frac{\sin nx}{n^2} - 6x \frac{\cos nx}{n^3} + \frac{6 \sin nx}{n^4} \right]_0^{\pi}$$

$$= \frac{2}{\pi} \left[x \cos nx - 6x \frac{\cos nx}{n^3} \right]_0^{\pi}$$

$$= \frac{2}{\pi} \left[\cos n\pi - 6 \cos n\pi \right]$$

$$= \frac{2}{\pi} \left[(-1)^n - 6(-1)^n \right]$$

Engineering Mathematics – III

51

$$f(x) = \frac{1}{2} \left[\frac{2}{6} \sin x + \frac{2}{6} \sin 2x + \frac{2}{6} \sin 3x + \dots \right]$$

Half Range Series :

To obtain a Fourier expansion of a function $f(x)$ for the range $(0, \pi)$ which is half the period of the fourier series. As it is immaterial what ever the function may be outside the range

$0 < x < \pi$, we extend the function to cover the range $-\pi < x < \pi$. So that the new function may be even or odd. The fourier expansion of such function of half the period consists sine or cosine term only.

Sine Series :

If it is required to expand $f(x)$ as a sine series in $0 < x < \pi$ we extend the function to the range $-\pi < x < \pi$, so that it will be an odd function.

The desired half-range sine series is given by

$$f(x) = \sum_{n=1}^{\infty} b_n \sin nx$$

$$\text{where } b_n = \frac{2}{\pi} \int_0^{\pi} f(x) \sin nx dx$$

Cosine Series :

If its is required to expand $f(x)$ as a cosine series in $0 < x < \pi$, We extend the function to the range $-\pi < x < \pi$, so that it will be an even function.

The desired half - range cosine series is given by

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos nx$$

$$\text{where } a_n = \frac{2}{\pi} \int_0^{\pi} f(x) \cos nx dx$$

$$a_0 = \frac{2}{\pi} \int_0^{\pi} f(x) dx$$

Example – 4 :

Find the half - range sine series for the function $f(x) = e^{ax}$ for $0 < x < \pi$

Solution :

$$f(x) = \sum_{n=1}^{\infty} b_n \sin nx$$

$$\text{where } b_n = \frac{2}{\pi} \int_0^{\pi} e^{ax} \sin nx dx$$

$$\begin{aligned}
 & \frac{2}{a^2} e^{ax} \sum_{n=1}^{\infty} (a \sin nx + n \cos nx) \\
 & - \frac{2}{a^2} e^{ax} \sum_{n=1}^{\infty} (a \sin n + n \cos n) \\
 & \frac{2}{a^2} \sum_{n=1}^{\infty} (1)^n e^{ax} \\
 & \frac{2n}{(a^2 - n^2)} 1 (1)^n e^{ax} \\
 & \frac{2(1 - e^{ax})}{(a^2 - 1)}, \quad \frac{2.2(1 - e^{ax})}{(a^2 - 2^2)} \\
 & b_1 = \frac{2}{a} \frac{1 - e^{ax}}{1 - \sin x}, \quad \frac{2(1 - e^{ax})}{\sin 2x} \dots
 \end{aligned}$$

Assignment

1. Find a fourier series to represent $f(x) = x, 0 < x < 2$
2. Find a fourier series to represent the function

$$f(x) = e^x, \text{ for } -\pi < x < \pi$$

$$1, \text{ for } x$$

3. Find the fourier series of the function $f(x) = 0, \text{ for } x$

$$1,$$

$$\text{for } 2 < x$$

4. Represent the following function by a fourier sine series $f(t) = t, 0 < t < \pi$

$$1, \text{ for } 0 < x$$

5. Find the fourier cosine series for the function $f(x) = x, 0 < x < \pi$

$$0, \text{ for } x$$



CHAPTER – 5

FINITE DIFFERENCE AND INTERPOLATION

Finite Difference :

Suppose we are given the following values of $y = f(x)$ for a set of values fx :

x	x_0	x_1	x_2	x_n
y	y_0	y_1	y_2	y_n

The interpolation is the technique of estimating the value of a function for any intermediate value of the independent variable. While the process of computing the value of the function outside the given range is called extrapolation.

Suppose that the function $y = f(x)$ is tabulated for the equally spaced values $x = x_0, x_0 + h, x_0 + 2h, \dots, x_0 + nh$ giving $y = y_0, y_1, \dots, y_n$. To determine the values of $f(x)$ for some intermediate values of x , the following two types of difference are found useful.

Forward difference - The differences

$$\Delta y_0 = y_1 - y_0$$

$$\Delta y_1 = y_2 - y_1$$

$$\Delta y_{n-1} = y_n - y_{n-1}$$

Similarly $\Delta^2 y_0 = \Delta y_1 - \Delta y_0$

$$\Delta^3 y_1 = \Delta^2 y_2 - \Delta^2 y_1$$

$$\Delta^n y_0 = \Delta^{n-1} y_1 - \Delta^{n-1} y_0$$

Forward difference table

Value of x	Value of y	1st diff.	2nd diff.	3rd diff.	4th diff.	5th diff.
x_0	y_0	Δy_0				
$x_0 + h$	y_1	Δy_1	$\Delta^2 y_0$			
$x_0 + 2h$	y_2	Δy_2	$\Delta^2 y_1$	$\Delta^3 y_0$		
$x_0 + 3h$	y_3	Δy_3	$\Delta^2 y_2$	$\Delta^3 y_1$	$\Delta^4 y_0$	
$x_0 + 4h$	y_4	Δy_4	$\Delta^2 y_3$	$\Delta^3 y_2$	$\Delta^4 y_1$	$\Delta^5 y_0$
$x_0 + 5h$	y_5					

54

Engineering Mathematics – III

Backward difference $\nabla y_1 = y_1 - y_0$

$$\nabla y_1 = y_1 - y_0$$

:

:

:

$$\nabla^n y_n = \nabla^{n-1} y_n - \nabla^{n-1} y_{n-1}$$

Backward difference table

Value of x	Value of y	1st diff.	2nd diff.	3rd diff.	4th diff.	5th diff.
x_0	y_0	Δy_0				
$x_0 + h$	y_1	Δy_1	$\Delta^2 y_0$			
$x_0 + 2h$	y_2	Δy_2	$\Delta^2 y_1$	$\Delta^3 y_0$		
$x_0 + 3h$	y_3	Δy_3	$\Delta^2 y_2$	$\Delta^3 y_1$	$\Delta^4 y_0$	
$x_0 + 4h$	y_4	Δy_4	$\Delta^2 y_3$	$\Delta^3 y_2$	$\Delta^4 y_1$	$\Delta^5 y_0$
$x_0 + 5h$	y_5					

Differences of a polynomial

We know that the expression of the form $f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$ where a 's are constant ($a_0 \geq 0$) and n is a positive integer is called a polynomial in x of degree n .

Theorem :

The 1st difference is a polynomial of degree n is of degree $n - 1$, the 2nd difference is of degree $n - 2$, and the n th difference is constant. While higher difference are equal to zero.

The converse of the theorem is also true which states that if n th difference of a function tabulated at equally spaced intervals are constant, the function is a polynomial of degree n .

Example – 1 :

Form the successive forward differences of ax^3 , the interval being h .

Solution :

Here $y = f(x) = ax^3$

We know that

$$\Delta y_0 = y_1 - y_0 = f(x+h) - f(x)$$

$$\begin{aligned} \Delta(ax^3) &= a(x+h)^3 - ax^3 \\ &= a(x^3 + 3x^2h + 3xh^2 + h^3) - ax^3 \\ &= a(3x^2h + 3xh^2 + h^3) \end{aligned}$$

Again, $\Delta_2 y_0 = \Delta y_1 - \Delta y_0$

$$\Delta_2(ax^3) = a\{3(x+h)^2h + 3(x+h)h^2 + h^3\} - a(3x^2h + 3xh^2 + h^3)$$

$$= a\{3x^2h + 6xh^2 + 3h^3 + 3xh^2 + 3h^3 + h^3 - 3x^2h - 3xh^2 - h^3\} = a\{6xh^2 + 6h^3\}$$

$$\Delta_3 y_0 = \Delta_2 y_1 = \Delta_2 y_0$$

$$\Delta_3 (ax^3) = a \{6(x+h)^2 + 6h^3\} - a \{6x^2 + 6h^3\}$$

$$\text{and } \Delta y_0 = \Delta_{y=\Delta y} = a \{6x^2 + 6h^3 + 6h^3 - 6x^2 - 6h^3\} = 6ah^3 = \text{Constant}$$

$$\Delta_4 (ax^3) = 6ah^3 - 6ah^3 = 0$$

Here it shows that the the third differences of a polynomial of third degree is constant & the higher difference & are zero.

Factorial Notation

A product of the form $x(x - 1)(x - 2) \dots (x - r + 1)$ is denoted by $[x]_r$ and is called a factorial.

In particular

$$[x] = x, [x]_2 = x(x - 1)$$

$$[x]_3 = x(x - 1)(x - 2)$$

$$[x]_n = x(x - 1)(x - 2) \dots (x - n + 1)$$

which is called a factorial polynomial or function.

The factorial notation is of special utility in the theory of first differences. It helps in finding the successive differences of a polynomials directly by simply rule of differentiation.

The result of differentiating $[x]_r$ is similar to that of differential x^r .

Example – 2 :

Estimate the missing term in the following table :

x	0	1	2	3	4

Solution : f(x) 1 3 9 8 1

Let the missing term by y_1 . The following is the difference table.

x	y	Δ	Δ_2	Δ_3	Δ_4
0	1				
1	3	2	4	$y_3 - 19$	
2	9	6	$y_3 - 15$		$124 - 4y_3$
3	y_3	$y_3 - 9$	$81 - 2y_3 + 9$	$105 - 3y_3$	
4	81	$81 - y_3$			

As only four entries y_0, y_1, y_2, y_4 are given, the function y can be represented by a third degree polynomial, here 4th order difference becomes zero, i.e.,

$$124 - 4y_3 = 0$$

$$\rightarrow y_3 = 31$$

Hence the missing term is 31.

Example – 3 :

Estimate the missing term in the following table :

x	0	1	2	3	4	5	6
y							

Solution : 5 11 22 40 -- 140 --

Let the missing term by y_4 & y_6 . The following is the difference table.

x :	y:	Δ	Δ_2	Δ_3	Δ_4	Δ_5
0	5					
1	11	6	5			
2	22	11	7	2	$y_4 - 67$	
3	40	18	$y_4 - 40$	$y_4 - 58$	$303 - 4y_4$	$370 - 5y_4$
4	y_4	$y_4 - 40$	$180 - 3y_4$	$238 - 3y_4$	$y_6 + 6y_4 -$	$y_6 + 10y_4 - 1001$
5	140	$140 - y_4$	$y_6 + y_4 -$	$y_6 + 3y_4 - 460$	698	
6	y_6	$y_6 - 140$	280			

~~As only four entries y_0, y_1, y_2, y_3 are given, the function y can be represented by a 4th degree polynomial & hence 5th difference becomes zero, i.e.,~~

$370 - 5y_4 = 0$ and $y_6 + 10y_4 - 1001 = 0$

Solving these, we get

$y_4 = 74$ and $y_6 = 261$

Newton’s Forward interpolation formula for equal intervals

Let the function $y = f(x)$ takes the values y_0, y_1, y_2, \dots corresponding to the values $x_0, x_1 + h, x_0 + 2h$ of x .

$$f(x_0 + nh) = y_0 + n \frac{\Delta y_0}{1!} + \frac{n(n-1)}{2!} \Delta^2 y_0 + \frac{n(n-1)(n-2)}{3!} \Delta^3 y_0 + \dots$$

Obs. This formula is used for interpolating the values of y near the beginning of a set of tabulated values and extrapolating values of y a little backward (i.e. to the left) of y_0 .

Newton’s backward interpolation formula for equal intervals

Let the function $y = f(x)$ takes the values y_0, y_1, y_2, \dots corresponding to the values $x_0, x_1 + h, x_0 + 2h$ of x .

$$f(x_n - nh) = y_n - n \frac{\Delta y_n}{1!} + \frac{n(n-1)}{2!} \Delta^2 y_n - \frac{n(n-1)(n-2)}{3!} \Delta^3 y_n + \dots$$

Obs. This formula is used for interpolating the values of y near the beginning of a set of tabulated values and extrapolating values of y a little backward (i.e. to the right) of y_n .

Engineering Mathematics – III

57

Example – 4 :

The table gives the distances in nautical miles of the visible horizon for the given heights in feet above the earth's surface.

x = height	100	150	200	250	300	350	400
y = distance	10.63	13.03	15.04	16.81	18.42	19.90	21.27

Find the values of y when (i) x = 218-ft.

Solution :

The difference table is as under :

x	y	Δ	Δ_2	Δ_3	Δ_4
100	10.63				
		2.40			
150	13.03		- 0.39		
		2.01		0.15	
200	15.04		- 0.24		- 0.07
		1.77		0.08	
250	16.81		- 0.16		- 0.05
		1.61		0.03	
300	18.42		- 0.13		- 0.01
		1.48		0.02	
350	19.90		- 0.11		
		1.37			
400	21.27				

- (i) If we take $x_0 = 200$, then $y_0 = 15.04$, $\Delta y_0 = 1.77$, $\Delta_2 y_0 = -0.16$, $\Delta_3 y_0 = 0.03$ etc.

$$\text{Since } x = 218 \text{ and } h = 50, n = \frac{x - x_0}{h} = \frac{218 - 200}{50} = 0.36$$

\ Using Newton's forward interpolation formula, we get

$$y_{218} = y_0 + n \Delta y_0 + \frac{n(n-1)}{1 \cdot 2} \Delta_2 y_0 + \frac{n(n-1)(n-2)}{1 \cdot 2 \cdot 3} \Delta_3 y_0 + \dots$$

$$f(218) = 15.04 + 0.36(1.77) + \frac{0.36(0.64)}{2} (-0.16) + \frac{0.36(0.64)(1.64)}{6} (0.03) \dots$$

- (ii) Since x = 410 is near the end of the table, we use Newton's backward interpolation formula.

$$\text{\ taking } x_n = 400, n = \frac{x - x_n}{h_n} = \frac{410 - 400}{50} = 0.2$$

Using the line of backward differences

$$Y_n = 21.27, \nabla_2 y_n = -0.11, \nabla_3 y_n = 0.02 \text{ etc.}$$

\ Newton's backward formula gives

$$y_{410} = y_{400} + n \nabla y_{200} + \frac{n(n-1)}{2} \nabla^2 y_{400} + \frac{n(n-1)(n-2)}{1.2.3} \nabla^3 y_{400} \dots$$

$$= 21.27 + 0.2(1.37) + \frac{0.2(1.2)}{2} (0.11) \dots = 21.53 \text{ nautical miles.}$$

Example – 5 :

Find the number of men getting wages between Rs. 10 and 15 from the following data :

Wages in Rs. 0–10	10–20	20–30	30–40
Frequency	9	30	42

Solution : First we prepare the cumulative frequency table, as follows :

Wages less than (x)	10	20	30	40
No. of men (y)	9	39	74	116

Now the difference table is

x	y	Δ	Δ ₂	Δ _s
10	9			
		30		
20	39		5	
		35		2
30	74		7	
		42		
40	116			

We shall find y_{15} i.e. number of men getting wages less than 15.

Taking $x_0 = 10, x = 15$, we have

$$n = \frac{x - x_0}{h} = \frac{15 - 10}{10 - 10} = 0.5$$

\ using Newton's forward interpolation formula, we get

$$y_{15} = y_{10} + n \Delta y_{10} + \frac{n(n-1)}{2!} \Delta^2 y_{10} + \frac{n(n-1)(n-2)}{3!} \Delta^3 y_{10}$$

$$= 9 + 0.5(30) + \frac{1(0.5)(-0.5)}{2} (26) + \frac{1(0.5)(-0.5)(-1.5)}{6} (5)$$

$$= 9 + 15 - 0.625 + 0.125 = 23.5 = 24 \text{ approx.}$$

Number of men getting wages between Rs. 10 and 15 = 24 – 10 = 14 approx.

Engineering Mathematics – III

59

Example – 6 :

Find the cubic polynomial which takes the following values :

x	0	1	2	3
f(x)	1	2	1	10

Solution :

The difference table is

x	f(x)	$\Delta f(x)$	$\Delta_2 f(x)$	$\Delta_3 f(x)$
0	1			
		1		
1	2		-2	
		-1		12
2	1		10	
		9		
3	10			

We take $x_0 = 0$ and $p = \frac{x-0}{h}$

Using Newton's forward interpolation formula, we get

$$f(x) = f(0) + \frac{x}{1} f'(0) + \frac{x(x-1)}{1 \cdot 2} f''(0) + \frac{x(x-1)(x-2)}{1 \cdot 2 \cdot 3} f'''(0)$$

$$= 1 + x(1) + \frac{x(x-1)(2)}{2} + \frac{x(x-1)(x-2)(12)}{6}$$

$= 2x^3 + 7x^2 + 6x + 1$, which is the required polynomial.

To compute $f(4)$, we take $x_n = 3$, $x = 4$ so that $p = \frac{x-x_n}{h} = 1$

Using Newton's backward interpolation formula, we get

$$f(4) = f(3) + n \nabla f(3) + \frac{n(n-1)}{1 \cdot 2} \nabla^2 f(3) + \frac{n(n-1)(n-2)}{1 \cdot 2 \cdot 3} \nabla^3 f(3)$$

$$= 10 + 9 + 10 + 12 + 41$$

which is the same value as that obtained by substituting $x = 4$ in the cubic polynomial above.

Obs. The above example shows that if a tabulated function is a polynomial, then interpolation and extrapolation give the same values.

Lagrange's Interpolation formula for unequal intervals :

$$f(x) = \frac{(x-x_1)(x-x_2)\dots(x-x_n)}{(x-x_1)(x_0-x_2)\dots(x_0-x_n)}$$

$$y_0 \frac{(x-x_1)(x-x_2)\dots(x-x_n)}{(x_0-x_1)(x_0-x_2)\dots(x_0-x_n)}$$

$$y_1 \dots \frac{(x-x_0)(x-x_2)\dots(x-x_{n-1})}{(x_1-x_0)(x_1-x_2)\dots(x_1-x_{n-1})}$$

Lagrange's Method for unequally spaced values of x :

$$x \frac{(y_1 y_2) \dots (y_1 y_n)}{(y_0 y_1) (y_0 y_2) \dots (y_0 y_n)} \frac{(y_0 y_2) \dots (y_0 y_n)}{(y_1 y_0) (y_1 y_2) \dots (y_1 y_n)}$$

$$\frac{(y_0 y_2) \dots (y_0 y_n)}{(y_n y_0) (y_n y_1) \dots (y_n y_{n-1})}$$

Example – 7 :

Use lagrange's interpolation formula to find the value of y when x = 10, if the following values of x & y are given.

Solution :

Here	x ₀ 5	x ₁ 6	x ₂ 9	x ₃ 11
and	y ₀ 12	y ₁ 13	y ₂ 14	y ₃ 16

Putting x = 10 and substituting the above value in Lagrange's formula, we get :

$$f(x) = \frac{(x-x_1)(x-x_2)(x-x_3)}{(x-x_0)(x-x_2)(x-x_3)} y_0 + \frac{(x-x_0)(x-x_2)(x-x_3)}{(x-x_1)(x-x_2)(x-x_3)} y_1$$

$$+ \frac{(x-x_0)(x-x_1)(x-x_3)}{(x-x_2)(x-x_1)(x-x_3)} y_2 + \frac{(x-x_0)(x-x_1)(x-x_2)}{(x-x_3)(x-x_1)(x-x_2)} y_3$$

$$f(10) = \frac{(10-6)(10-9)(10-11)}{(5-6)(5-9)(5-11)} \cdot 12 + \frac{(10-5)(10-9)(10-11)}{(6-5)(6-9)(6-11)} \cdot 13$$

$$+ \frac{(10-5)(10-6)(10-11)}{(9-5)(9-6)(9-11)} \cdot 14 + \frac{(10-5)(10-6)(10-9)}{(11-5)(11-6)(11-9)} \cdot 16$$

$$= 41(1) + 51(1) + (4)(4)(6) 12 + 4(3)(5) 13$$

$$\frac{54(1) 14 54116 48 65 280 320}{43(2)65224 1524 60}$$

$$= 2 - 4.33 + 11.66 + 5.33 = 14.66$$

Engineering Mathematics – III

Example – 8 :

Apply lagrange’s method to find the value of x when f(x) = 15 from the given data.

x	5	6	9	11
f(x)	12	13	14	16

Solution :

Here

$$x_0 = 5, \quad x_1 = 6, \quad x_2 = 9, \quad x_3 = 11$$

$$y_0 = 12, \quad y_1 = 13, \quad y_2 = 14, \quad y_3 = 16$$

Taking y = 15 and using the above results in Lagrange’s inverse interpolation formula.

$$x = f(x) \frac{(y - y_1)(y - y_2)(y - y_3)}{(y - y_0)(y - y_1)(y - y_2)} x_0 + \frac{(y - y_0)(y - y_2)(y - y_3)}{(y - y_1)(y - y_2)(y - y_3)} x_1$$

$$+ \frac{(y - y_0)(y - y_1)(y - y_3)}{(y - y_2)(y - y_1)(y - y_3)} x_2 + \frac{(y - y_0)(y - y_1)(y - y_2)}{(y - y_3)(y - y_0)(y - y_1)} x_3$$

$$= \frac{(15 - 13)(15 - 14)(15 - 16)}{(15 - 12)(15 - 13)(15 - 14)} \cdot 5 + \frac{(15 - 12)(15 - 14)(15 - 16)}{(13 - 13)(12 - 14)(12 - 16)} \cdot 6$$

$$+ \frac{(15 - 12)(15 - 13)(15 - 16)}{(14 - 12)(14 - 13)(14 - 16)} \cdot 9 + \frac{(15 - 12)(15 - 13)(15 - 14)}{(16 - 12)(16 - 13)(16 - 16)} \cdot 11$$

$$= \frac{21(1)}{(1)(2)(4)} + \frac{31(1)}{5 \cdot 4(-3)} + \frac{32(1)}{6 \cdot 2(2)} + \frac{3 \cdot 2 \cdot 1}{4 \cdot 3 \cdot 2} \cdot 11$$

$$= 5 + 27 + 11$$

$$= 46 - \frac{3}{2} - \frac{3}{4} = 1.25 - 6 + 13.5 + 2.75 = 17.5 - 6 = 11.5$$

Assignment

1. Find a cubic polynomial which takes the following values

x	0	1	2	3
f(x)	1	2	1	10

2. Given the values

x	5	7	11	13	17
y	150	392	1452	2366	5202

Evaluate y_9 using Lagrange’s formula.

3. Given $\sin 45^\circ = 0.7071$, $\sin 50^\circ = 0.7660$, $\sin 55^\circ = 0.8192$ and $\sin 60^\circ = 0.8660$. Find $\sin 52^\circ$ using Newton’s forward interpolation formula.



CHAPTER – 6

NUMERICAL SOLUTION OF EQUATION

1. An expression of the form

$$f(x) = a_0 x^n + a_1 x^{n-1} + \dots + a_{n-1} x + a_n$$

where $a_0, a_1, a_2, \dots, a_n \neq 0$ are constant and n is a positive integer is called a polynomial in x of degree n .

2. The polynomial $f(x) = 0$

For example (1) $2x^2 + x - 13x + 6 = 0$

(2) $x^3 - 4x + 9 = 0$

are called algebraic equation.

3. Transcendental equation -

If $f(x)$ is a functions other than algebraic function such as trigonometric, logarithmic, exponential etc. then $f(x)$ is called transcendental function.

4. Root of an equation -

The value of x which satisfied $f(x) = 0$ is called the root of the equation.

Geometrically a root of the equation $f(x) = 0$ & $y = 0$ is the value of x where the graph meet the y -axis.

5. Solution of an equation -

The process of finding a root of an equation is known as the solution of an equation.

6. Different methods to solve the equations.

(a) Analytical method

(b) Graphical method

(c) Numerical method

7. Limitation of analytical method

This methods produce very exact and accurate results. But it fails in many cases such as it fails to find roots of transcendental equation.

8. Limitation of graphical method -

This methods are simple but these methods produce result to a low degree accuracy.

9. Advantages of Numerical method –

This methods are often of a repetitive nature. These consist in repeated execution of the same process. Where each step the result of proceeding step is used. This is known as

iteration process and is repeated till the result is obtained to a desired degree of accuracy.

Engineering Mathematics – III

63

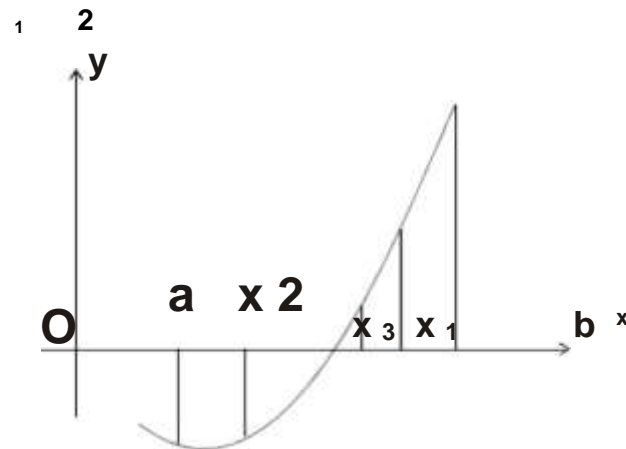
The followings are some Numerical methods to find root of algebraic and transcendental equation –

- (1) Bisection method
- (2) Newton – Raphson method

Bisection method :

This method consists of locating a root of the equation $f(x) = 0$ between a and b . If $f(x)$ is continuous between a and b , and $f(a)$ and $f(b)$ are of opposite signs then there is a root between a and b . from the graph $f(a)$ is negative and $f(b)$ is positive then there is a root lies between a and b . The first approximation to the root is

$$x_1 = \frac{a+b}{2}$$



if $f(x) = 0$, then x_1 is the root of equation $f(x) = 0$. Otherwise the root lies between a and x_1 or x_1 and b according to $f(x_1)$ is positive or negative. Then we bisect the interval and continue the process until the root is found to desired accuracy.

In the fig.1 $f(x)$ is +ve, so the root lies between x_1 and b . Then the 2nd approximation to the root is $x_2 = \frac{x_1 + b}{2}$. If $f(x)$ is -ve, the root lies between a and x_1 . So the third

approximation to the root is $x_3 = \frac{a + x_1}{2}$ and so on.

Example – 1 :

(a) Find a root of the equation

$x^3 - 4x - 9 = 0$ using the bisection method correct to three decimal places.

Solution :

2	2.5	2.625	2.75	3
$f(2) = -ve$	$f(2.5) = -ve$	$f(2.625) = -ve$	$f(2.75) = +ve$	$f(3) = +ve$

Let $f(x) = x^3 - 4x - 9$

$$f(2) = (2)^3 - 4(2) - 9 = -9 \text{ (-ve)}$$

$$f(3) = (3)^3 - 4(3) - 9 = 6 \text{ (+ve)}$$

a root lies between 2 and 3.

64

Engineering Mathematics – III

First approximate to the root is

$$x_1 = 2.5$$

$$f(x) = (2.5)^3 - 4(2.5) - 9 = -3.375 \text{ (-ve)}$$

the root lies between 2.5 and 3. The second approximation to the root is

$$x_2 = \frac{2.5 + 3}{2} = 2.75$$

$$f(x) = (2.75)^3 - 4(2.75) - 9 = 0.7969 \text{ (+ve)}$$

the root lies between 2.5 and 2.75

$$\text{So } x_3 = \frac{2.5 + 2.75}{2} = 2.625$$

$$f(2.625) = (2.625)^3 - 4(2.625) - 9 = -1.4121 \text{ (-ve)}$$

the root lies between 2.625 and 2.75.

$$x_4 = \frac{2.625 + 2.75}{2} = 2.6875$$

Repeating this process, the successive approximation are

$$x_5 = 2.71875, x_6 = 2.70313, x_7 = 2.71094, x_8 = 2.70703, x_9 = 2.70508,$$

$$x_{10} = 2.70605, x_{11} = 2.70654, x_{12} = 2.70642. \text{ Hence the root is } 2.7064.$$

Example – 2 :Find the root of the equation $x \log_{10} x = 1.2$ which lies between 2 and 3, using bisection method taking 2 stages.**Solution :**

$$\text{Let } f(x) = x \log_{10} x - 1.2 = 2 \times \log_{10} 2 - 1.2 \\ = 2 \times .3010 - 1.2 = -0.5979 \text{ (-ve)}$$

$$f(3) = 3 \times \log_{10} 3 - 1.2 = 0.2314 \text{ (+ve)}$$

the root lies between 2 and 3

1

$$x_1 = \frac{2 + 3}{2} = 2.5$$

$$f(2.5) = 2.5 (\log_{10} 2.5) - 1.2 = -0.205 \text{ (-ve)}$$

the root lies between 2.5 and 3

$$\text{Hence the root is } 2.75. \quad x_2 = \frac{2.5 + 3}{2} = 2.75$$

Example – 3 :By using the bisection method, find an approximate root of the equation $\sin x = \frac{1}{x}$, that lies between $x = 1$ and $x = 1.5$ (measured in radians). Carry out

computations upto the 7th stage.

Engineering Mathematics – III

65

Solution.

Let $f(x) = x \sin x - 1$. We know that $V = 57.3^\circ$

Since $f(1) = 1 \times \sin(1) - 1 = \sin(57.3^\circ) - 1 = -0.15849$

and $f(1.5) = 1.5 \times \sin(1.5) - 1 = 1.5 \times \sin(85.95^\circ) - 1 = 0.49625$;

a root lies between 1 and 1.5.

\ first approximation to the root is $x_1 = \frac{1}{2}(1 + 1.5) = 1.25$.

Then $f(x_1) = (1.25) \sin(1.25) - 1 = 1.25 \sin(71.625^\circ) - 1 = 0.18627$ and $f(1) < 0$.

\ a root lies between 1 and $x_1 = 1.25$.

Thus the second approximation to the root is $x_2 = \frac{1}{2}(1 + 1.25) = 1.125$.

Then $f(x_2) = 1.125 \sin(1.125) - 1 = 1.125 \sin(64.46^\circ) - 1 = 0.01509$ and $f(1) < 0$.

\ a root lies between 1 and $x_2 = 1.125$.

Thus the third approximation to the root is $x = \frac{1}{3}(1 + 1.125) = 1.0625$

Then $f(x_3) = 1.0625 \sin(1.0625) - 1 = 1.0625 \sin(60.88^\circ) - 1 = -0.0718 < 0$

and $f(x_2) > 0$, i.e. now the root lies between $x_4 = 1.0625$ and $x_2 = 1.125$.

\ fourth approximation to the root is $x = \frac{1}{4}(1.0625 + 1.125) = 1.09375$

Then $f(x_4) = -0.02836 < 0$ and $f(x_2) > 0$,

i.e., the root lies between $x_4 = 1.09375$ and $x_2 = 1.125$.

\ fifth approximation to the root is $x_5 = \frac{1}{2}(1.09375 +$

$1.125) = 1.10937$ Then $f(x) = -0.00664 < 0$ and $f(x) > 0$.

\ the root lies between $x_5 = 1.10937$ and $x_2 = 1.125$.

Thus the sixth approximation to the root is

$\frac{1}{2}$

$$x_6 = \frac{1}{2}(1.10937 + 1.125) = 1.11719$$

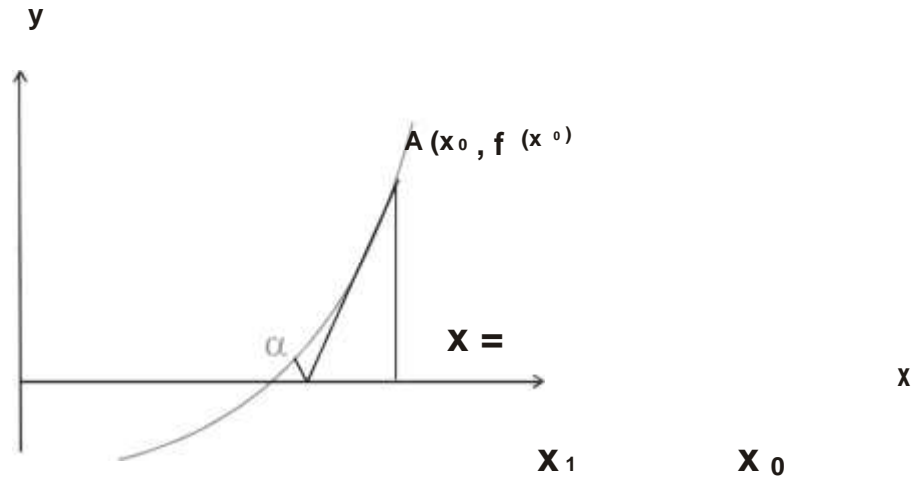
\ the root lies between $x_5 = 1.10937$ and $x_6 = 1.11719$.

Thus the seventh approximation to the root is $x_7 = \frac{1}{2}(1.10937 + 1.11719) =$

1.11328 Hence the desired approximation to the root is 1.11328.

Newton-Raphson Method

Engineering Mathematics – III



In this method, instead of taking two initial rough approximations to the root as in the previous two methods, a single rough approximation x_0 to the root is taken. The following formula, known as Newton-Raphson formula or Newton iteration formula, gives successive approximations.

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} \quad (1)$$

Putting $n = 0, 1, 2, \dots$ etc. in the above formula (1), we get the successive approximations as follows.

$$x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

$$x_2 = x_1 - \frac{f(x_1)}{f'(x_1)}$$

$$x_3 = x_2 - \frac{f(x_2)}{f'(x_2)}$$

This method is useful in cases of large values of $f'(x)$ i.e., when the graph of $f(x)$ while crossing the x-axis is nearly vertical.

The process of finding successive approximations to the root (i.e., x_1, x_2, x_3 etc.) may be continued till the root is found to desired degree of accuracy.

Example – 4 :

Find by Newton's method, a root of the equation $x^3 - 3x + 1 = 0$ correct to 3 decimal places.

Solution : Let $f(x) = x^3 - 3x + 1$

$$f(1) = 1^3 - 3 + 1 = -1$$

→ The root of $f(x)$ lies between 1 & 2

Engineering Mathematics – III

67

Let $x = 1.5$, Also $f(x) = 3x^2 - 3$

$$f(x) = (3x^2 - 3)$$

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

$$= x_n - \frac{3x_n^2 - 3}{6x_n}$$

$$= x_n - \frac{3(x_n^2 - 1)}{6x_n} = x_n - \frac{x_n^2 - 1}{2x_n} \quad \dots(1)$$

Putting $n = 0$ in (i), the first approximation x_1 is given by

$$x_1 = \frac{2x_0^3 - 1}{3x_0^2} = \frac{2(1.5)^3 - 1}{3(1.5)^2} = \frac{2(3.375) - 1}{3(2.25)} = \frac{5.75}{6.75} = 0.85185$$

Putting $n = 1$ in (i), the second approximation x_2 is given by

$$x_2 = \frac{2x_1^3 - 1}{3x_1^2} = \frac{2(0.85185)^3 - 1}{3(0.85185)^2} = \frac{2(0.613) - 1}{3(0.726)} = \frac{0.226}{2.178} = 0.1037$$

Example – 5 :

Find the Newton's method, the real root of the equation $3x = \cos x + 1$

Solution : Let $f(x) = 3x - \cos x - 1$

$$f(0) = -2 = -ve, f(1) = 3 - 0.5403 - 1 = 1.4597 = +ve$$

So a root of $f(x) = 0$ lies between 0 and 1. It is nearer to 1. Let us take $x_0 = 0.6$.

Also $f(x) = 3 + \sin x$

\ Newton's iteration formula gives

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} = \frac{3x_n - \cos x_n - 1}{x_n \sin x_n - \cos x_n} \quad \dots(i)$$

Putting $n = 0$, the first approximation x_1 is given by

$$x_1 = \frac{x_0 \sin x_0 - \cos x_0 - 1}{3 \sin x_0} = \frac{(0.6) \sin(0.6) - \cos(0.6) - 1}{3 \sin(0.6)}$$

$$= \frac{0.6(0.5729) - 0.82533 - 1}{3(0.5729)} = \frac{0.34374 - 1.82533}{1.7187} = \frac{-1.48159}{1.7187} = -0.862$$

Putting $n = 1$ in (i), the second approximation is

$$x_2 = \frac{x_1 \sin x_1 - \cos x_1 - 1}{3 \sin x_1} = \frac{0.6071 \sin(0.6071) - \cos(0.6071) - 1}{3 \sin(0.6071)}$$

$$= \frac{0.6071(0.57049) - 0.8213 - 1}{3(0.57049)} = \frac{0.3453 - 1.8213}{1.71147} = \frac{-1.476}{1.71147} = -0.862$$

Clearly, $x_1 = x_2$.

Hence the desired root is 0.6071 correct to four decimal places.

Assignment

1. Find a root of the following equations, using the bisection method correct to three decimal places.
 - (a) $x^3 - x - 11 = 0$
 - (b) $x^4 - x - 10 = 0$
2. Find by Newton-Raphson method, a root of the following equations correct to 3 decimal places.
 - (a) $x^3 - 3x + 1 = 0$
 - (b) $3x^3 - 9x^2 + 8 = 0$
3. Using Newton-Raphson method to evaluate the following

(a) $\frac{1}{32}$

(b) $\sqrt{41}$

□ □ □